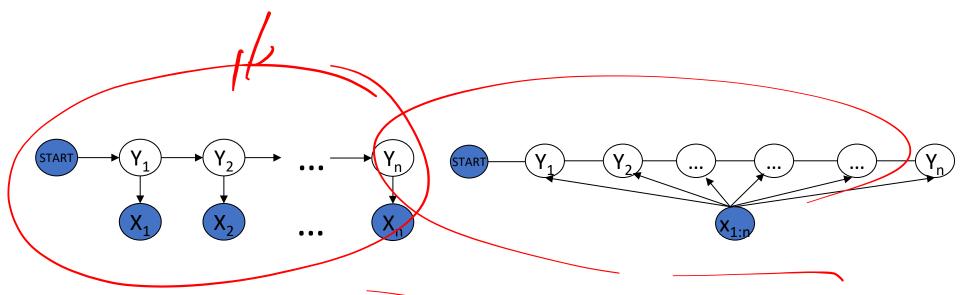
CRF (cont'd) + Intro to Topic Modeling

Kayhan Batmanghelich

Slides Credit:

Matt Gormley (2016)

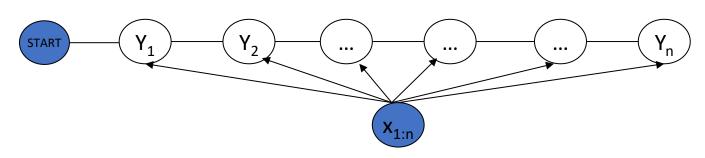
Review: Generative vs Discriminative



$$P(\mathbf{x}_{1:n}, \mathbf{y}_{1:n}) = \prod_{i=1}^{n} P(x_i|y_i)P(y_i|y_{i-1})$$

$$P(\mathbf{y}_{1:n}|\mathbf{x}_{1:n}) = \frac{1}{Z(\mathbf{x}_{1:n})} \prod_{i=1}^{n} \phi(y_i, y_{i-1}, \mathbf{x}_{1:n}) = \frac{1}{Z(\mathbf{x}_{1:n}, \mathbf{w})} \prod_{i=1}^{n} \exp(\mathbf{w}^T \mathbf{f}(y_i, y_{i-1}, \mathbf{x}_{1:n}))$$

Review: Conditional Random Field

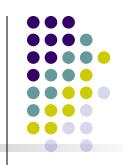


$$P(\mathbf{y}|\mathbf{x}) = \frac{1}{Z(\mathbf{x}, \lambda, \mu)} \exp(\sum_{i=1}^{n} (\sum_{k} \lambda_{k} f_{k}(y_{i}, y_{i-1}, \mathbf{x}) + \sum_{l} \mu_{l} g_{l}(y_{i}, \mathbf{x})))$$

$$= \underbrace{\sum_{i=1}^{n} (\lambda^{T} \mathbf{f}(y_{i}, y_{i-1}, \mathbf{x}) + \mu^{T} \mathbf{g}(y_{i}, \mathbf{x})))}_{l}$$
where $Z(\mathbf{x}, \lambda, \mu) = \sum_{\mathbf{y}} \exp(\sum_{i=1}^{n} (\lambda^{T} \mathbf{f}(y_{i}, y_{i-1}, \mathbf{x}) + \mu^{T} \mathbf{g}(y_{i}, \mathbf{x})))$

When can I ignore $Z(x, \lambda, \mu)$:

- Computing $\underset{\mathbf{y}}{\text{arg max}} P(\mathbf{y}|\mathbf{x}; \lambda, \mu)$?
- Computing $\max_{\lambda,\mu} \log P(y|x; \lambda, \mu)$?



Given $\{(\mathbf{x}_d, \mathbf{y}_d)\}_{d=1}^N$, find λ^* , μ^* such that

$$\lambda*, \mu* = \arg\max_{\lambda,\mu} L(\lambda,\mu) = \arg\max_{\lambda,\mu} \prod_{d=1}^{N} P(\mathbf{y}_{d}|\mathbf{x}_{d},\lambda,\mu)$$

$$= \arg\max_{\lambda,\mu} \prod_{d=1}^{N} \frac{1}{Z(\mathbf{x}_{d},\lambda,\mu)} \exp(\sum_{i=1}^{n} (\lambda^{T} \mathbf{f}(y_{d,i},y_{d,i-1},\mathbf{x}_{d}) + \mu^{T} \mathbf{g}(y_{d,i},\mathbf{x}_{d})))$$

$$= \arg\max_{\lambda,\mu} \sum_{d=1}^{N} (\sum_{i=1}^{n} (\lambda^{T} \mathbf{f}(y_{d,i},y_{d,i-1},\mathbf{x}_{d}) + \mu^{T} \mathbf{g}(y_{d,i},\mathbf{x}_{d})) - \log Z(\mathbf{x}_{d},\lambda,\mu))$$

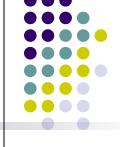
exponential family is the expectation of the Computing the gradient w.r.t λ : sufficient statistics?

$$\nabla_{\lambda} L(\lambda, \mu) = \sum_{d=1}^{N} \left(\sum_{i=1}^{n} \mathbf{f}(y_{d,i}, y_{d,i-1}, \mathbf{x}_d) - \sum_{\mathbf{y}} \left(P(\mathbf{y} | \mathbf{x}_d) \sum_{i=1}^{n} (y_{d,i}, y_{d,i-1}, \mathbf{x}_d) \right) \right)$$

© Eric Xing @ CMU, 2005-2015

Gradient of the log-partition function in an





$$\nabla_{\lambda} L(\lambda, \mu) = \sum_{d=1}^{N} \left(\sum_{i=1}^{n} \mathbf{f}(y_{d,i}, y_{d,i-1}, \mathbf{x}_d) - \sum_{\mathbf{y}} \left(P(\mathbf{y} | \mathbf{x}_d) \sum_{i=1}^{n} \mathbf{f}(y_i, y_{i-1}, \mathbf{x}_d) \right) \right)$$

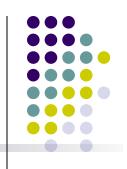
- Computing the model expectations:
 - Requires exponentially large number of summations: Is it intractable?

$$\sum_{\mathbf{y}} (P(\mathbf{y}|\mathbf{x}_d) \sum_{i=1}^n \mathbf{f}(y_i, y_{i-1}, \mathbf{x}_d)) = \sum_{i=1}^n (\sum_{\mathbf{y}} \mathbf{f}(y_i, y_{i-1}, \mathbf{x}_d) P(\mathbf{y}|\mathbf{x}_d))$$

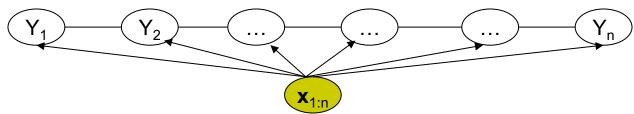
$$= \sum_{i=1}^n \sum_{y_i, y_{i-1}} \mathbf{f}(y_i, y_{i-1}, \mathbf{x}_d) P(y_i, y_{i-1}|\mathbf{x}_d)$$

Expectation of **f** over the corresponding marginal probability of neighboring nodes!!

- Tractable!
 - Can compute marginals using the sum-product algorithm on the chain

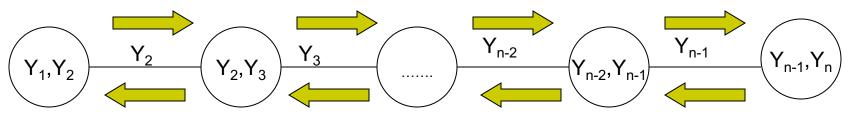


Computing marginals using junction-tree calibration:



Junction Tree Initialization:

$$\alpha^{0}(y_{i}, y_{i-1}) = \exp(\lambda^{T} \mathbf{f}(y_{i}, y_{i-1}, \mathbf{x}_{d}) + \mu^{T} \mathbf{g}(y_{i}, \mathbf{x}_{d}))$$



• After calibration.

$$P(y_i, y_{i-1}|\mathbf{x}_d) \propto \alpha(y_i, y_{i-1})$$

Also called forward-backward algorithm

$$\Rightarrow P(y_i, y_{i-1} | \mathbf{x}_d) = \frac{\alpha(y_i, y_{i-1})}{\sum_{y_i, y_{i-1}} \alpha(y_i, y_{i-1})} = \alpha'(y_i, y_{i-1})$$



Computing feature expectations using calibrated potentials:

$$\sum_{y_i,y_{i-1}} \mathbf{f}(y_i,y_{i-1},\mathbf{x}_d) P(y_i,y_{i-1}|\mathbf{x}_d) = \sum_{y_i,y_{i-1}} \mathbf{f}(y_i,y_{i-1},\mathbf{x}_d) \alpha'(y_i,y_{i-1})$$

• Now we know how to compute (λ, μ) :

$$\nabla_{\lambda} L(\lambda, \mu) = \sum_{d=1}^{N} (\sum_{i=1}^{n} \mathbf{f}(y_{d,i}, y_{d,i-1}, \mathbf{x}_{d}) - \sum_{\mathbf{y}} (P(\mathbf{y}|\mathbf{x}_{d}) \sum_{i=1}^{n} \mathbf{f}(y_{i}, y_{i-1}, \mathbf{x}_{d})))$$

$$= \sum_{d=1}^{N} (\sum_{i=1}^{n} (\mathbf{f}(y_{d,i}, y_{d,i-1}, \mathbf{x}_{d}) - \sum_{y_{i}, y_{i-1}} \alpha'(y_{i}, y_{i-1}) \mathbf{f}(y_{i}, y_{i-1}, \mathbf{x}_{d})))$$

Learning can now be done using gradient ascent:

$$\lambda^{(t+1)} = \lambda^{(t)} + \eta \nabla_{\lambda} L(\lambda^{(t)}, \mu^{(t)})$$

$$\mu^{(t+1)} = \mu^{(t)} + \eta \nabla_{\mu} L(\lambda^{(t)}, \mu^{(t)})$$





 In practice, we use a Gaussian Regularizer for the parameter vector to improve generalizability

$$\lambda *, \mu * = \left(\arg \max_{\lambda, \mu} \sum_{d=1}^{N} \log P(\mathbf{y}_d | \mathbf{x}_d, \lambda, \mu) - \frac{1}{2\sigma^2} (\lambda^T \lambda + \mu^T \mu) \right)$$

- In practice, gradient ascent has very slow convergence
 - Alternatives:
 - Conjugate Gradient method
 - Limited Memory Quasi-Newton Methods

General CRFs, Hidden-state CRFs

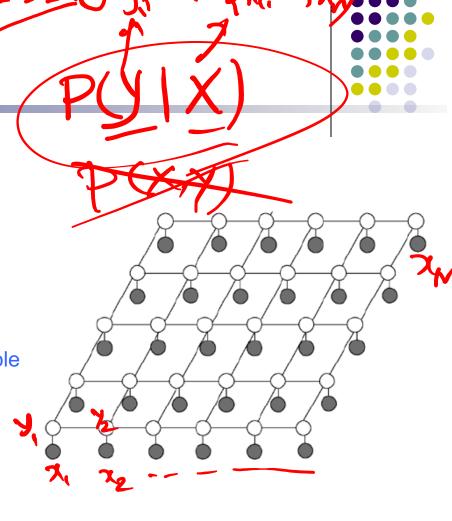
2. CASE STUDY: IMAGE SEGMENTATION (COMPUTER VISION)

Other CRFs

 So far we have discussed only 1dimensional chain CRFs

Inference and learning: exact

- We could also have CRFs for arbitrary graph structure
 - E.g: Grid CRFs
 - Inference and learning no longer tractable
 - Approximate techniques used
 - MCMC Sampling
 - Variational Inference
 - Loopy Belief Propagation
 - We will discuss these techniques soon



Applications of CRF in Vision



Stereo Matching

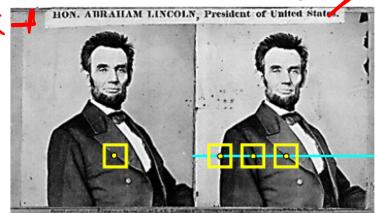


Image Segmentation

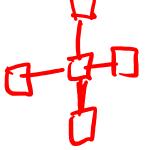
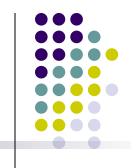




Image Restoration



$P(y|x) = II \phi(y,x) II \phi(y,y,y)$ Application: Image Segmentation

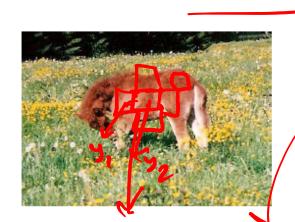


 $\phi_i(y_i, x) \in \mathbb{R}^{\approx 1000}$: local image features, e.g. bag-of-words $\rightarrow \langle w_i, \phi_i(y_i, x) \rangle$: local classifier (like logistic-regression)

 $\phi_{i,j}(y_i,y_j) = \llbracket y_i \quad y_j \rrbracket \in \mathbb{R}^1$: test for same label

 $\rightarrow \langle w_{ij}, \phi_{ij}(y_i, y_j) \rangle$: penalizer for label changes (if $w_{ij} > 0$)

combined: $\operatorname{argmax}_y p(y|x)$ is smoothed version of local cues

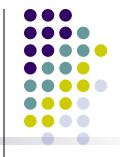




local classification

local + smoothness

Case Study: Image Segmentation

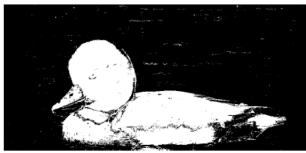


- Image segmentation (FG/BG) by modeling of interactions btw RVs
 - Images are noisy.
 - Objects occupy continuous regions in an image.





Input image



Pixel-wise separate optimal labeling



Locally-consistent joint optimal labeling

Unary Term Pairwise Term
$$Y^* = \underset{y \in \{0,1\}^n}{\operatorname{arg\,max}} \left[\sum_{i \in S} V_i(y_i, X) + \sum_{i \in S} \sum_{j \in N_i} V_{i,j}(y_i, y_j) \right].$$

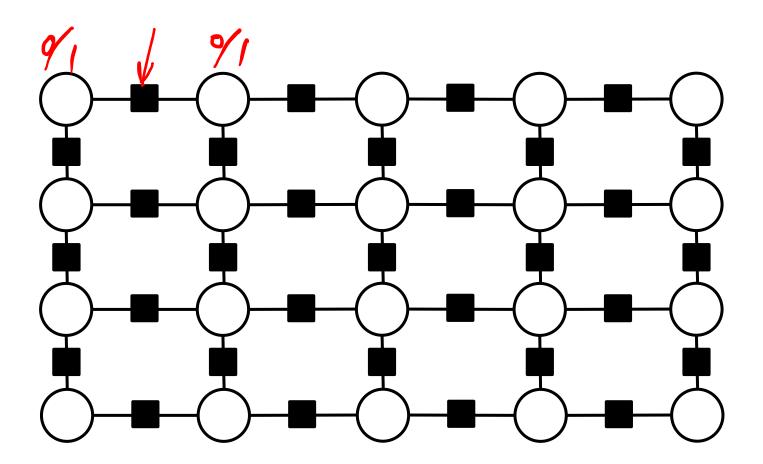
Y: labels

X: data (features)

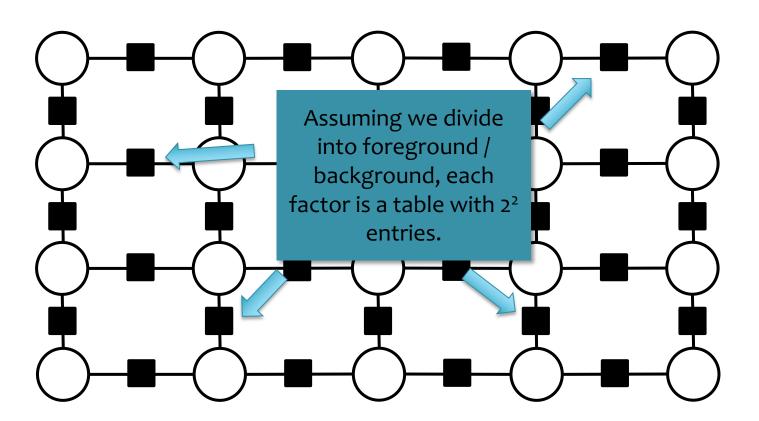
S: pixels

 N_i : neighbors of pixel i

Suppose we want to image segmentation using a grid model

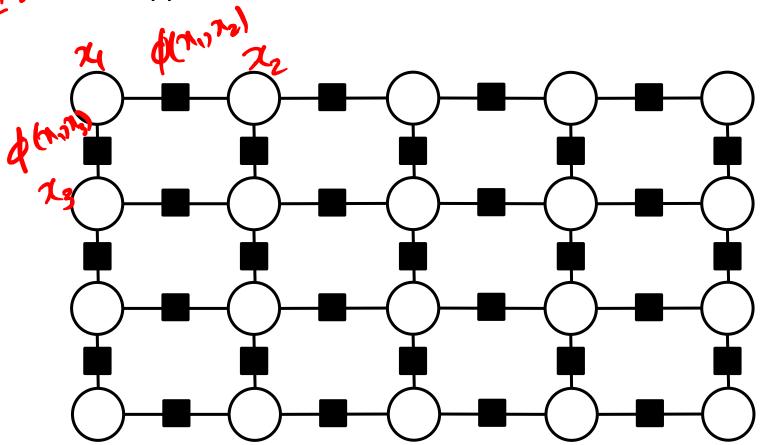


Suppose we want to image segmentation using a grid model



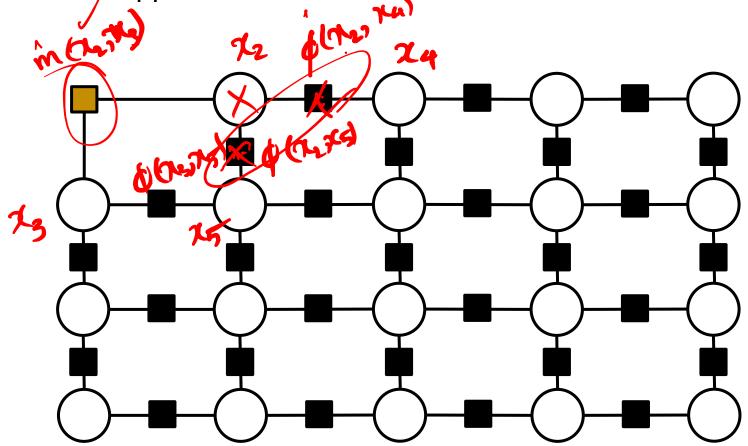
Grid CRF

Suppose we want to image segmentation using a grid model Vhat happens when we run variable elimination?

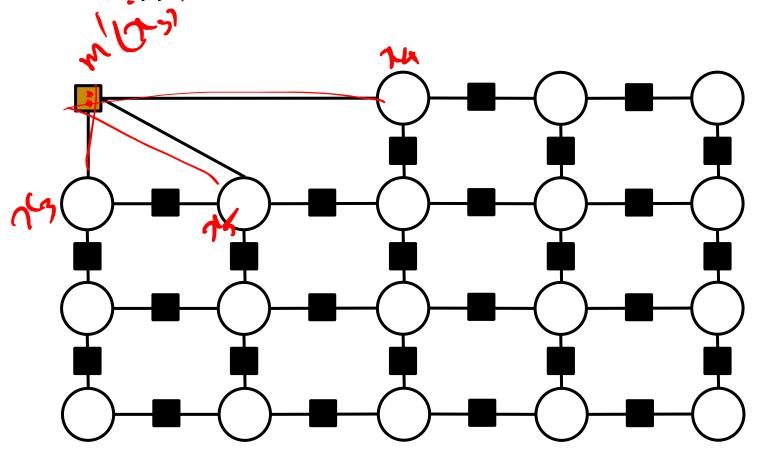


Suppose we want to image segmentation using a grid model

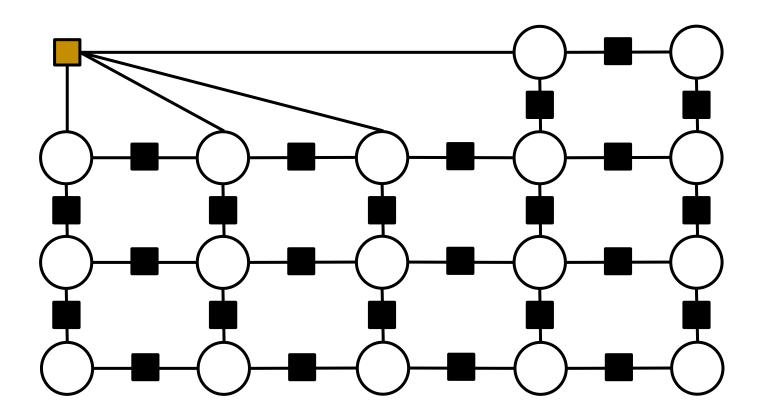
• What, happens when we run variable elimination?



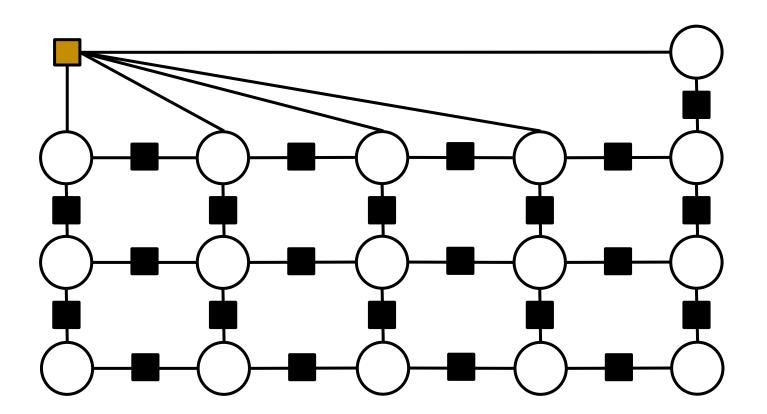
- Suppose we want to image segmentation using a grid model
- What happens when we run variable elimination?



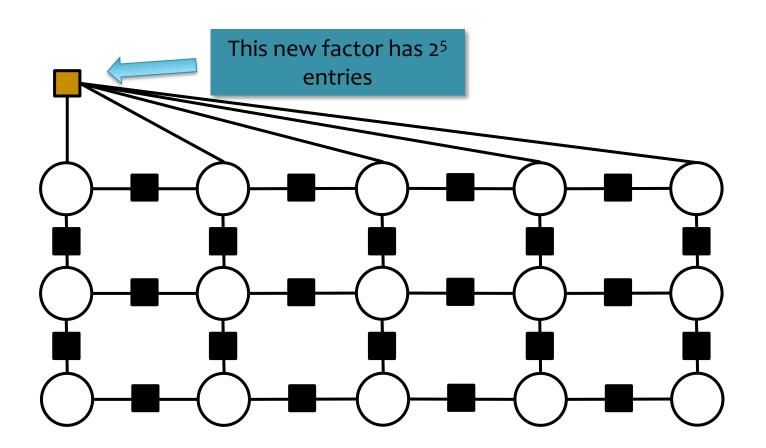
- Suppose we want to image segmentation using a grid model
- What happens when we run variable elimination?



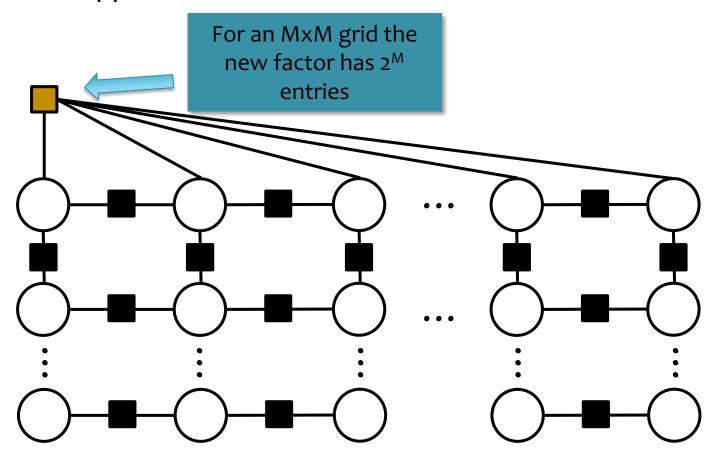
- Suppose we want to image segmentation using a grid model
- What happens when we run variable elimination?



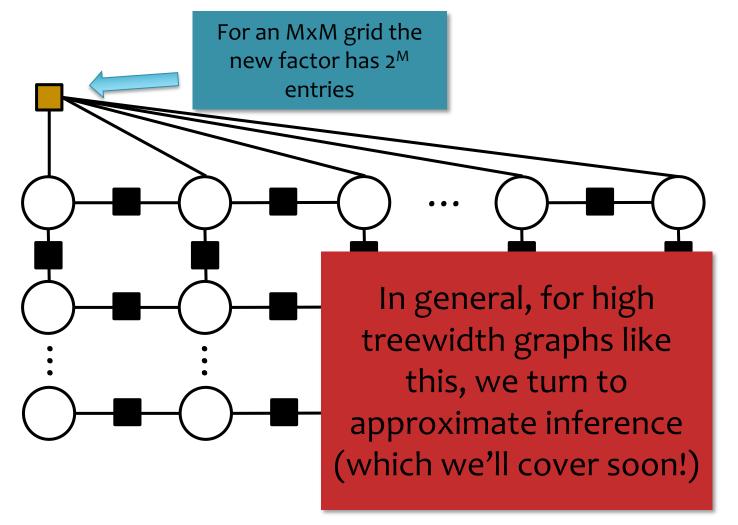
- Suppose we want to image segmentation using a grid model
- What happens when we run variable elimination?



- Suppose we want to image segmentation using a grid model
- What happens when we run variable elimination?



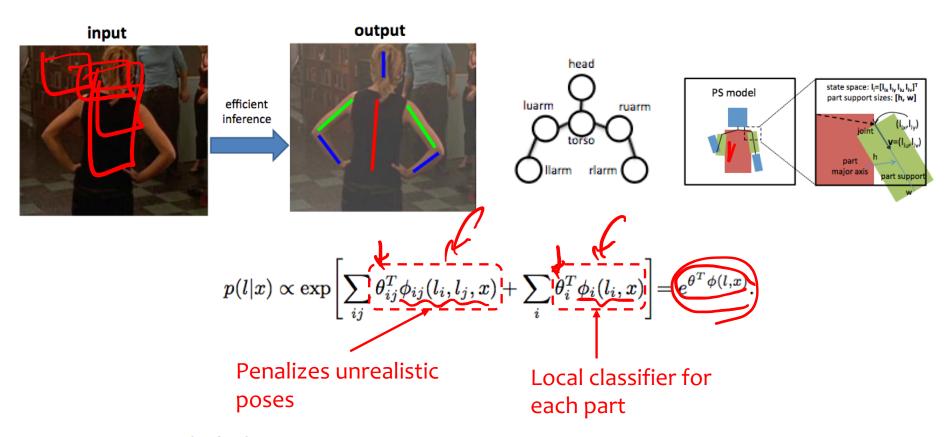
- Suppose we want to image segmentation using a grid model
- What happens when we run variable elimination?



- Suppose we want to image segmentation using a grid model
- What happens when we run variable elimination?



Application: Pose Estimation



 $\operatorname{argmax}_y p(y|x)$ is cleaned up version of local prediction

Feature Functions for CRF in Vision

- $\phi_i(y_i, x)$: local representation, high-dimensional $\rightarrow \langle w_i, \phi_i(y_i, x) \rangle$: local classifier
- $\phi_{i,j}(y_i, y_j)$: prior knowledge, low-dimensional $\rightarrow \langle w_{ij}, \phi_{ij}(y_i, y_j) \rangle$: penalize outliers

learning adjusts parameters:

- unary w_i : learn local classifiers and their importance
- binary w_{ij} : learn importance of smoothing/penalization

 $\operatorname{argmax}_y p(y|x)$ is cleaned up version of local prediction

Data consists of images x and labels y.



pigeon



leopard



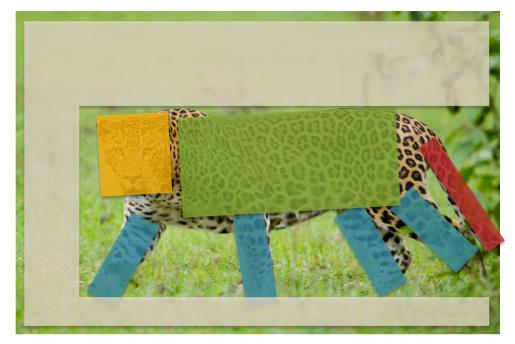
rhinoceros



llama

Data consists of images x and labels y.

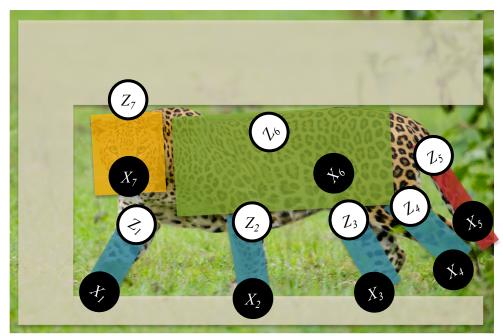
- Preprocess data into "patches"
- Posit a latent labeling z describing the object's parts (e.g. head, leg, tail, torso, grass)
- Define graphical model with these latent variables in mind
- z is not observed at train or test time



leopard

Data consists of images x and labels y.

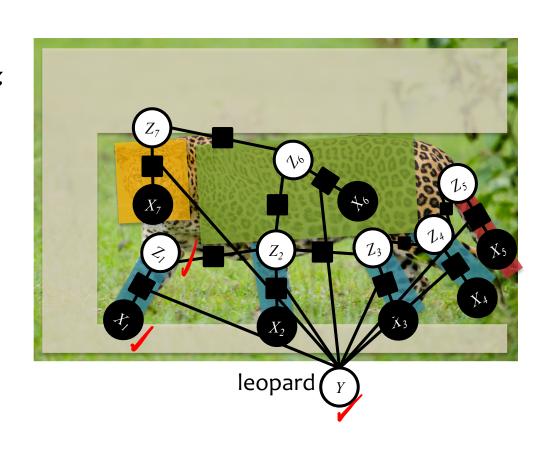
- Preprocess data into "patches"
- Posit a latent labeling z describing the object's parts (e.g. head, leg, tail, torso, grass)
- Define graphical model with these latent variables in mind
- z is not observed at train or test time



leopard (y)

Data consists of images x and labels y.

- Preprocess data into "patches"
- Posit a latent labeling z describing the object's parts (e.g. head, leg, tail, torso, grass)
- Define graphical model with these latent variables in mind
- z is not observed at train or test time



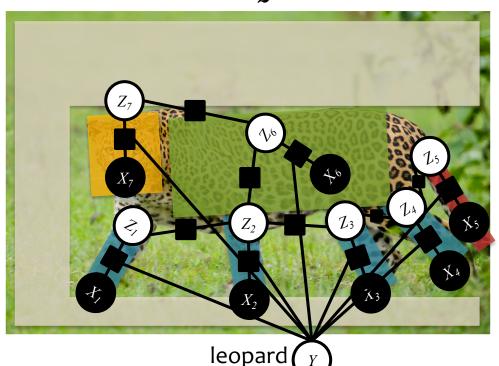
Hidden-state CRFs P(y|x)

Data:
$$\mathcal{D} = \{ \widehat{\boldsymbol{x}^{(n)}}, \widehat{\boldsymbol{y}^{(n)}} \}_{n=1}^{N}$$



Joint model:
$$p_{m{ heta}}(m{y},m{z}\midm{x}) = rac{1}{Z(m{x},m{ heta})}\prod_{lpha}\psi_{lpha}(m{y}_{lpha},m{z}_{lpha},m{x})$$

Marginalized model:
$$p_{\boldsymbol{\theta}}(\boldsymbol{y} \mid \boldsymbol{x}) = \sum_{\boldsymbol{z}} p_{\boldsymbol{\theta}}(\boldsymbol{y}, \boldsymbol{z} \mid \boldsymbol{x})$$



Hidden-state CRFs

$$\mathcal{D} = \{oldsymbol{x}^{(n)}, oldsymbol{y}^{(n)}\}_{n=1}^N$$

$$p_{m{ heta}}(m{y}, m{z} \mid m{x}) = rac{1}{Z(m{x}, m{ heta})} \prod_{lpha} \psi_{lpha}(m{y}_{lpha}, m{z}_{lpha}, m{x})$$

Marginalized model:
$$p_{\boldsymbol{\theta}}(\boldsymbol{y} \mid \boldsymbol{x}) = \sum_{\boldsymbol{z}} p_{\boldsymbol{\theta}}(\boldsymbol{y}, \boldsymbol{z} \mid \boldsymbol{x})$$

We can train using gradient based methods:

(the values x are omitted below for clarity)

$$\begin{split} \frac{d\ell(\boldsymbol{\theta}|\mathcal{D})}{d\boldsymbol{\theta}} &= \sum_{n=1}^{N} \left(\mathbb{E}_{\boldsymbol{z} \sim p_{\boldsymbol{\theta}}(\cdot|\boldsymbol{y}^{(n)})}[f_{j}(\boldsymbol{y}^{(n)}, \boldsymbol{z})] - \mathbb{E}_{\boldsymbol{y}, \boldsymbol{z} \sim p_{\boldsymbol{\theta}}(\cdot, \cdot)}[f_{j}(\boldsymbol{y}, \boldsymbol{z})] \right) \\ &= \sum_{n=1}^{N} \sum_{\alpha} \left(\sum_{\boldsymbol{z}_{\alpha}} p_{\boldsymbol{\theta}}(\boldsymbol{z}_{\alpha} \mid \boldsymbol{y}^{(n)}) f_{\alpha, j}(\boldsymbol{y}_{\alpha}^{(n)}, \boldsymbol{z}_{\alpha}) - \sum_{\boldsymbol{y}_{\alpha}, \boldsymbol{z}_{\alpha}} p_{\boldsymbol{\theta}}(\boldsymbol{y}_{\alpha}, \boldsymbol{z}_{\alpha}) f_{\alpha, j}(\boldsymbol{y}_{\alpha}, \boldsymbol{z}_{\alpha}) \right) \\ &\text{Inference on} \end{split}$$

clamped factor graph

Learning and Inference Summary

	Learning	Marginal Inference	MAP Inference
нмм	Just counting	Forward- backward	Viterbi
MEMM	Gradient based – decomposes and doesn't require inference (GLIM)	Forward- backward	Viterbi
Linear-chain CRF	Gradient based – doesn't decompose because of $Z(x)$ and requires marginal inference	Forward- backward	Viterbi
General CRF	Gradient based – doesn't decompose because of $Z(x)$ and requires (approximate) marginal inference	(approximate methods)	(approximate methods)
HCRF	Gradient based – same as General CRF	(approximate methods)	(approximate methods)

Summary

- HMM:
 - Pro: Easy to train
 - Con: Misses out on rich features of the observations
- MEMM:
 - Pro: Fast to train and supports rich features
 - Con: Suffers (like the HMM) from the label bias problem
- Linear-chain CRF:
 - Pro: Defeats the label bias problem with support for rich features
 - Con: Slower to train
- MBR Decoding:
 - the principled way to account for a loss function when decoding from a probabilistic model
- Generative vs. Discriminative:
 - gen. is better if the model is well-specified
 - disc. is better if the model is misspecified
- General CRFs:
 - Exact inference won't suffice for high treewidth graphs
 - More general topologies can capture intuitions about variable dependencies
- HCRF:
 - Training looks very much like CRF training
 - Incorporation of hidden variables can model domain specific knowledge

Introduction to Topic Modeling

Topic Modeling

Motivation:

Suppose you're given a massive corpora and asked to carry out the following tasks

- Organize the documents into thematic categories
- Describe the evolution of those categories over time
- Enable a domain expert to analyze and understand the content
- Find **relationships** between the categories
- Understand how authorship influences the content



Topic Modeling

Motivation:

Suppose you're given a massive corpora and asked to carry out the following tasks

- Organize the documents into thematic categories
- Describe the evolution of those categories over time
- Enable a domain expert to analyze and understand the content
- Find relationships between the categories
- Understand how authorship influences the content

Topic Modeling:

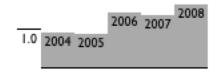
A method of (usually unsupervised) discovery of latent or hidden structure in a corpus

- Applied primarily to text corpora, but techniques are more general
- Provides a modeling toolbox
- Has prompted the exploration of a variety of new **inference methods** to accommodate **large-scale datasets**

Topic Modeling

Dirichlet-multinomial regression (DMR) topic model on ICML (Mimno & McCallum, 2008)

Topic 0 [0.152]



problem, optimization, problems, convex, convex optimization, linear, semidefinite programming, formulation, sets, constraints, proposed, margin, maximum margin, optimization problem, linear programming, programming, procedure, method, cutting plane, solutions

Topic 54 [0.051]



decision trees, trees, tree, decision tree, decision, tree ensemble, junction tree, decision tree learners, leaf nodes, arithmetic circuits, ensembles modts, skewing, ensembles, anytime induction decision trees, trees trees, random forests, objective decision trees, tree learners, trees grove, candidate split

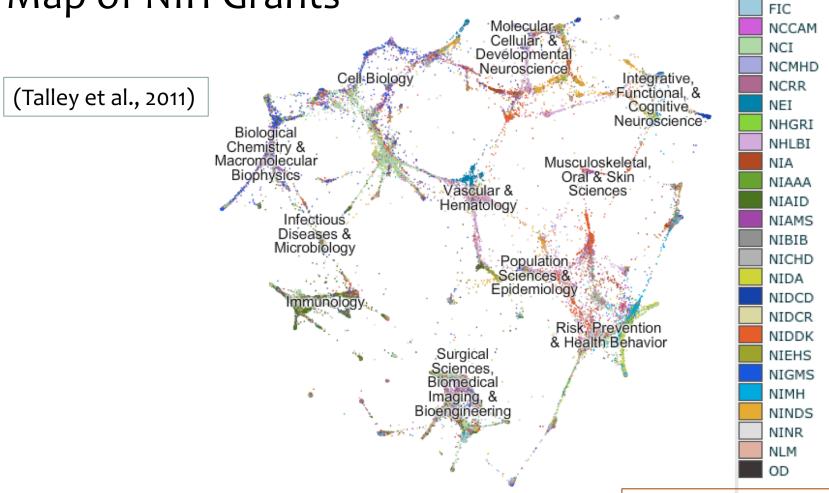
Topic 99 [0.066]



inference, approximate inference, exact inference, markov chain, models, approximate, gibbs sampling, variational, bayesian, variational inference, variational bayesian, approximation, sampling, methods, exact, bayesian inference, dynamic bayesian, process, mcmc, efficient http://www.cs.umass.edu/~mimno/icml100.html

Topic Modeling

Map of NIH Grants

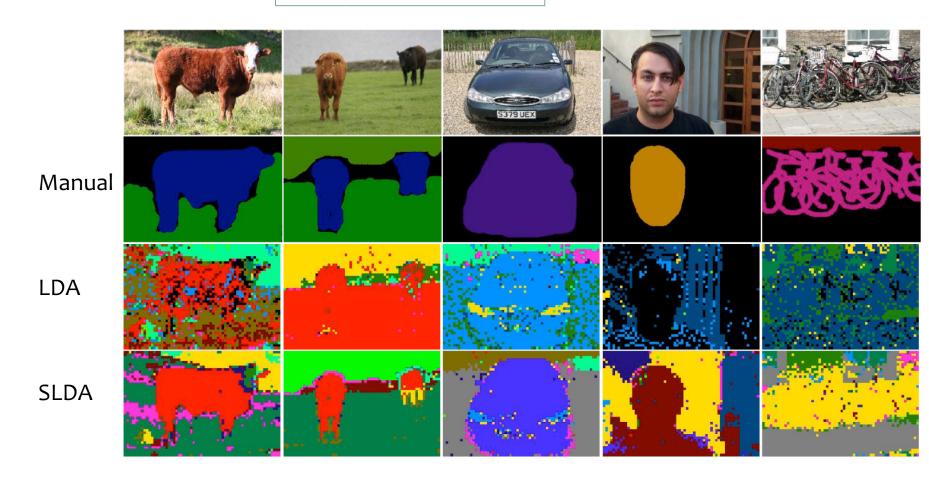


https://app.nihmaps.org/

Other Applications of Topic Models

Spacial LDA

(Wang & Grimson, 2007)



Outline

- Applications of Topic Modeling
- Review: Latent Dirichlet Allocation (LDA)
 - 1. Beta-Bernoulli
 - 2. Dirichlet-Multinomial
 - 3. Dirichlet-Multinomial Mixture Model
 - 4. LDA
- Contrast of methods for Inference / Learning
 - Exact inference
 - EM
 - Monte Carlo EM
 - Gibbs sampler
 - Collapsed Gibbs sampler
- Extensions of LDA
 - Correlated topic models
 - Dynamic topic models
 - Polylingual topic models
 - Supervised LDA

Beta-Bernoulli Model

Beta Distribution

$$f(\phi|\alpha,\beta) = \frac{1}{B(\alpha,\beta)} x^{\alpha-1} (1-x)^{\beta-1}$$

$$\begin{array}{c} \alpha = 0.1, \beta = 0.9 \\ -\alpha = 0.5, \beta = 0.5 \\ -\alpha = 1.0, \beta = 1.0 \\ -\alpha = 5.0, \beta = 5.0 \\ -\alpha = 10.0, \beta = 5.0 \\ -\alpha = 10.0, \beta = 5.0 \\ \end{array}$$

Beta-Bernoulli Model

Generative Process

```
\phi \sim \text{Beta}(\alpha, \beta) \qquad [draw \ distribution \ over \ words] For each word n \in \{1, \dots, N\} x_n \sim \text{Bernoulli}(\phi) \qquad [draw \ word]
```

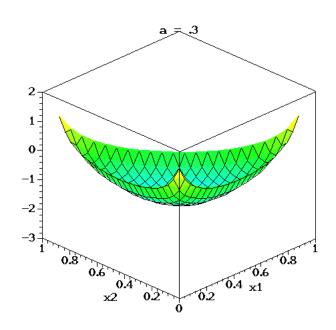
Example corpus (heads/tails)

Н	Т	Т	Н	Н	Т	Т	Н	Н	Н
X ₁	X ₂	X ₃	X ₄	X ₅	x ₆	X ₇	x ₈	x ₉	X ₁₀

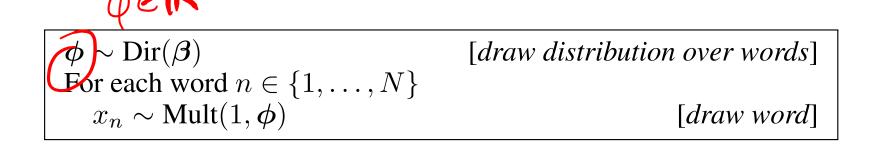
Dirichlet Distribution

Dirichlet Distribution

$$p(\vec{\phi}|\alpha) = \frac{1}{B(\alpha)} \prod_{k=1}^{K} \phi_k^{\alpha_k - 1} \quad \text{where } B(\alpha) = \frac{\prod_{k=1}^{K} \Gamma(\alpha_k)}{\Gamma(\sum_{k=1}^{K} \alpha_k)}$$



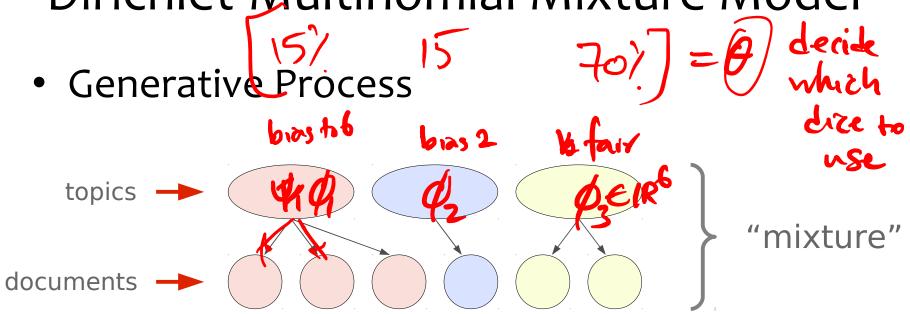
Generative Process



Example corpus

the	he	is	the	and	the	she	she	is	is
X ₁	X ₂	X ₃	X ₄	X ₅	x ₆	X ₇	x ₈	X ₉	X ₁₀

Dirichlet-Multinomial Mixture Model



Example corpus

the	he	is
X ₁₁	X ₁₂	X ₁₃

the	and	the
X ₂₁	X ₂₂	X ₂₃

she	she	is	is
X ₃₁	X ₃₂	X ₃₃	X ₃₄

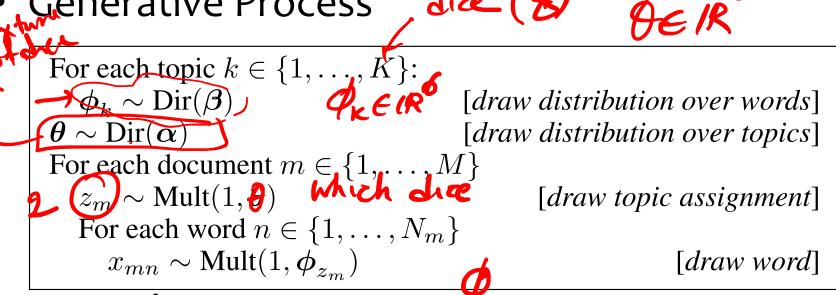
Document 1

Document 2

Document 3

Dirichlet-Multinomial Mixture Model

dice (8) Generative Process



Example corpus

the	he	is
X ₁₁	X ₁₂	X ₁₃

the	and	the	
X ₂₁	X ₂₂	X ₂₃	

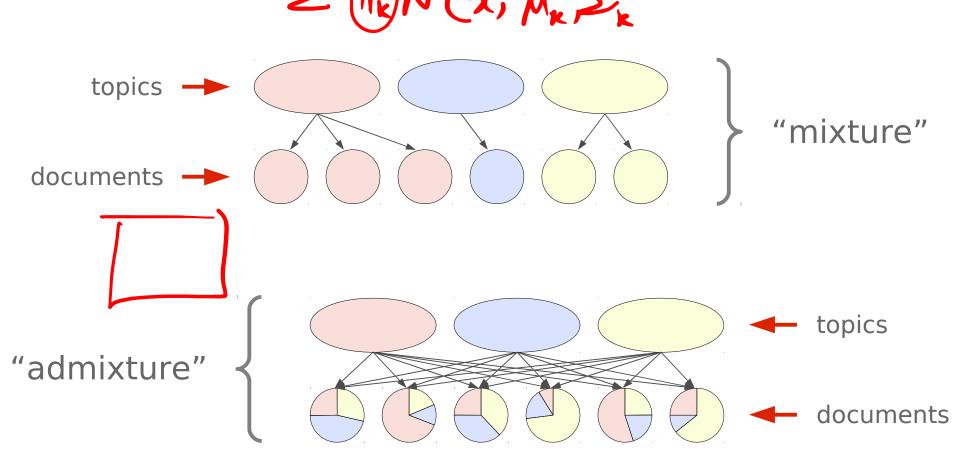
she	she	is	is
X ₃₁	X ₃₂	X ₃₃	X ₃₄

Document 1

Document 2

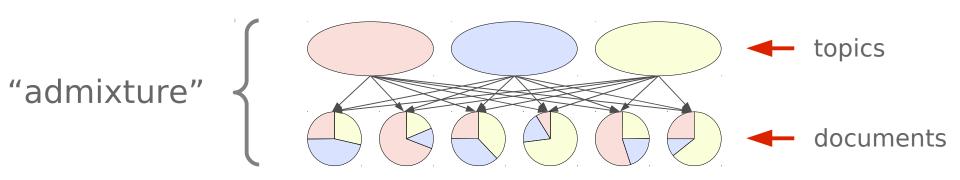
Document 3

Mixture vs. Admixture (LDA)



Diagrams from Wallach, JHU 2011, slides

Generative Process



Example corpus

the	he	is
X ₁₁	X ₁₂	X ₁₃

Document 1	l
Document	1

the	and	the
X ₂₁	X ₂₂	X ₂₃

Document 2

she	she	is	is
X ₃₁	X ₃₂	X ₃₃	X ₃₄

Document 3

Generative Process

```
For each topic k \in \{1, \dots, K\}:  \phi_k \sim \operatorname{Dir}(\beta) \qquad [draw \ distribution \ over \ words]  For each document m \in \{1, \dots, M\}  \theta_m \sim \operatorname{Dir}(\alpha) \qquad [draw \ distribution \ over \ topics]  For each word n \in \{1, \dots, N_m\}  z_{mn} \sim \operatorname{Mult}(1, \theta_m) \qquad [draw \ topic \ assignment]   x_{mn} \sim \phi_{z_{mi}} \qquad [draw \ word]
```

Example corpus

the	he	is
X ₁₁	X ₁₂	X ₁₃

the	and	the
X ₂₁	X ₂₂	X ₂₃

she	she	is	is
X ₃₁	X ₃₂	X ₃₃	X ₃₄

Document 1

Document 2

Document 3

Plate Diagram

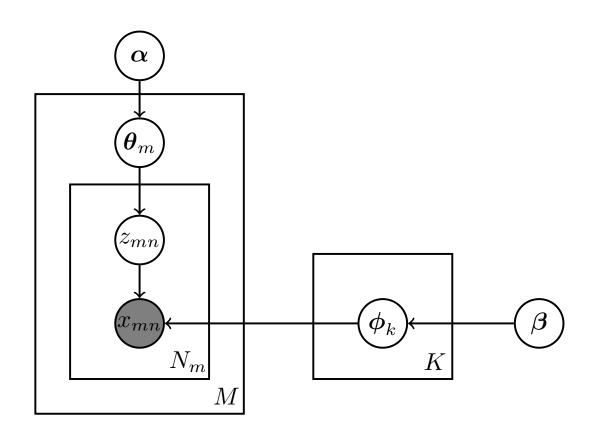
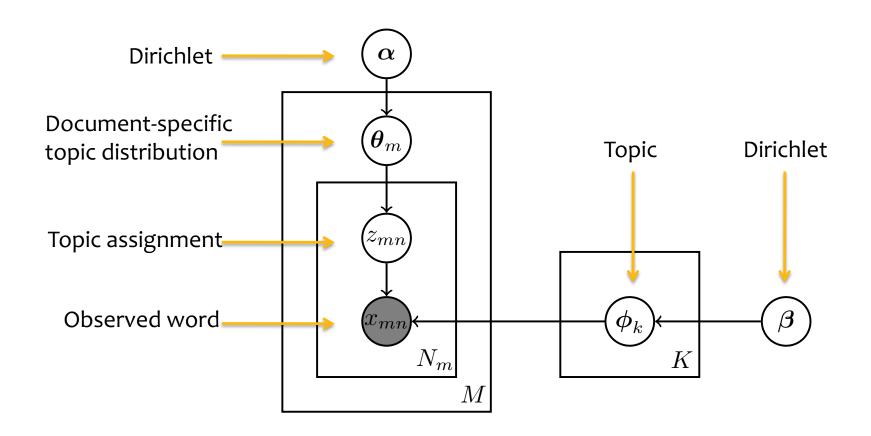
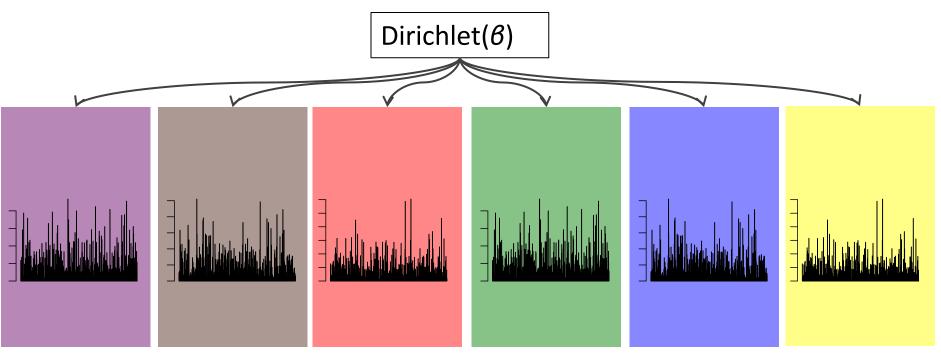
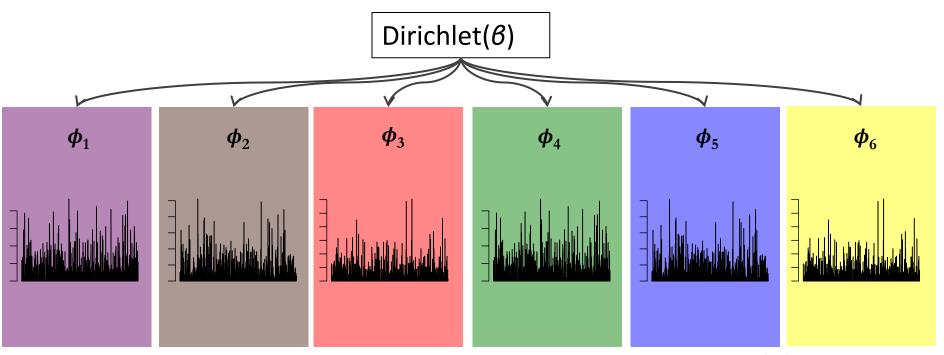


Plate Diagram

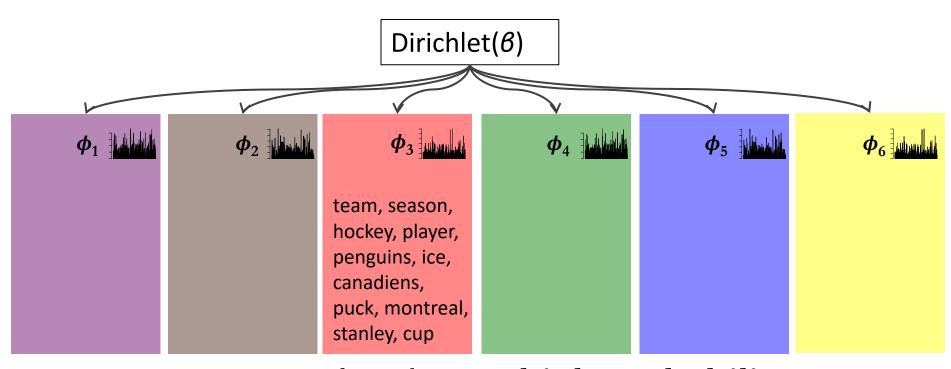




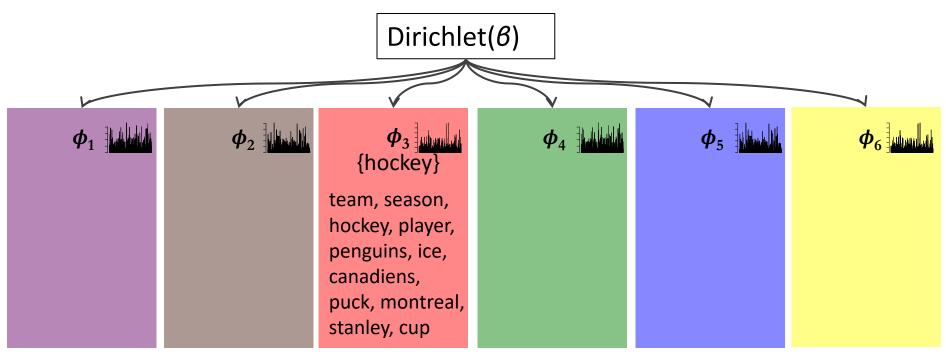
- The generative story begins with only a Dirichlet prior over the topics.
- Each **topic** is defined as a **Multinomial distribution** over the vocabulary, parameterized by $\phi_{\mathbf{k}}$



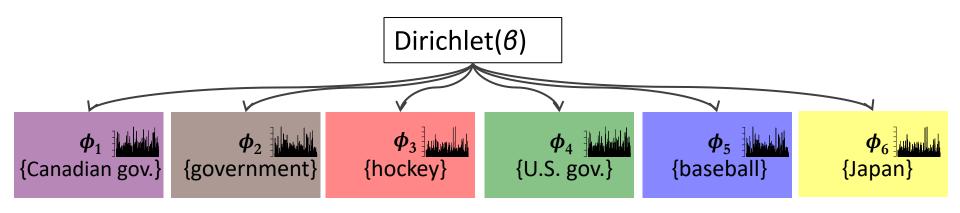
- The generative story begins with only a Dirichlet prior over the topics.
- Each **topic** is defined as a **Multinomial distribution** over the vocabulary, parameterized by $\phi_{\mathbf{k}}$



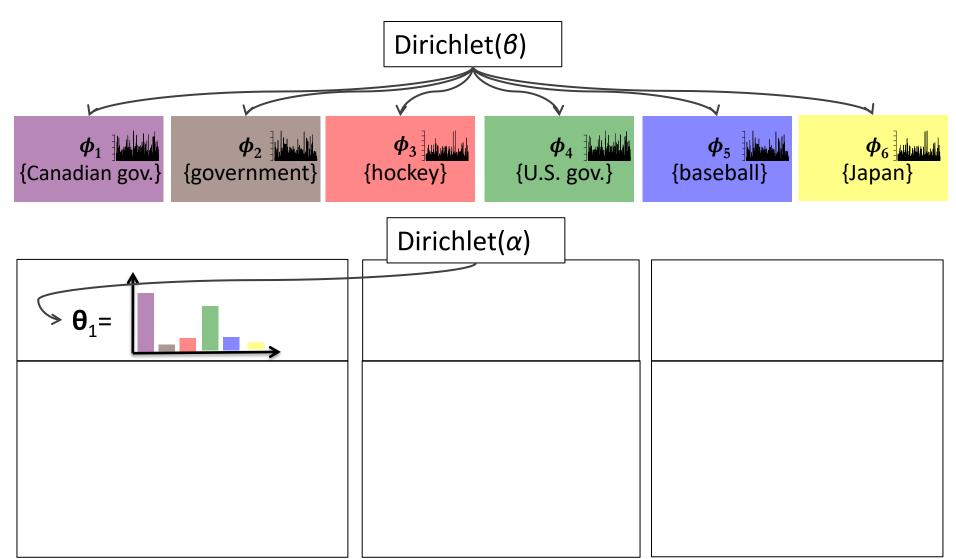
 A topic is visualized as its high probability words.

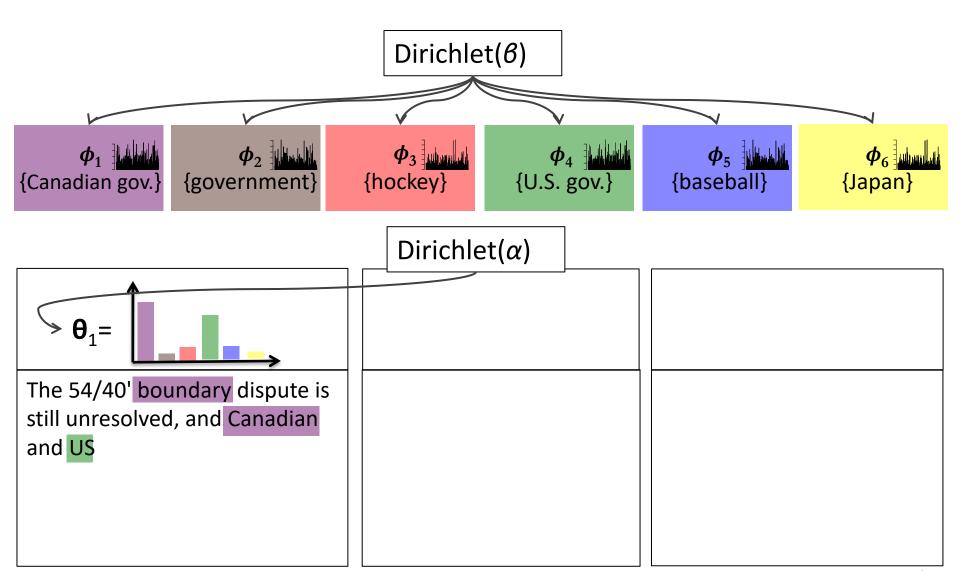


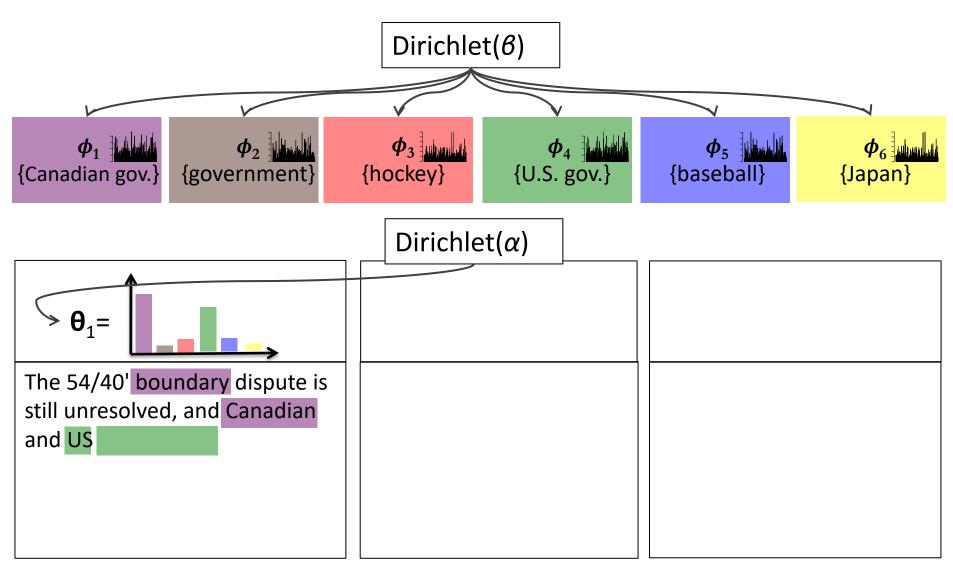
- A topic is visualized as its high probability words.
- A pedagogical label is used to identify the topic.

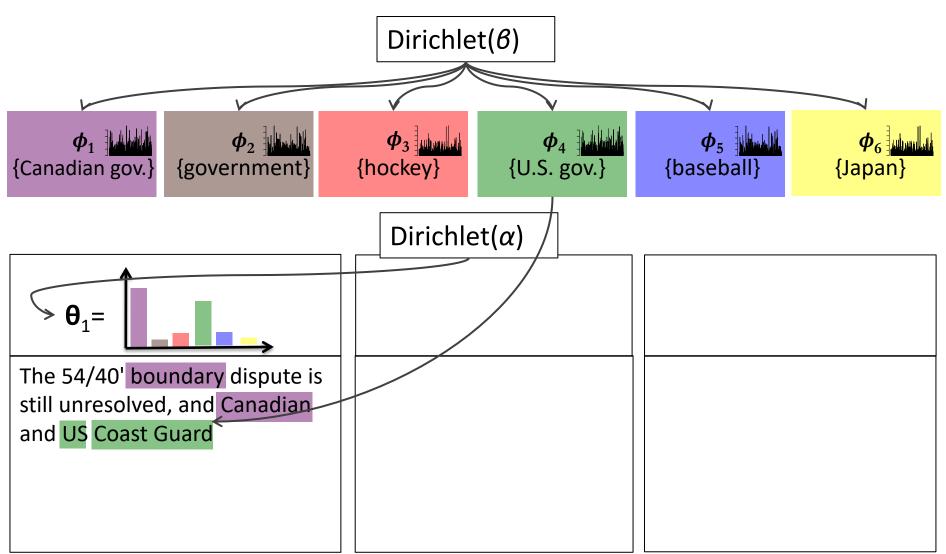


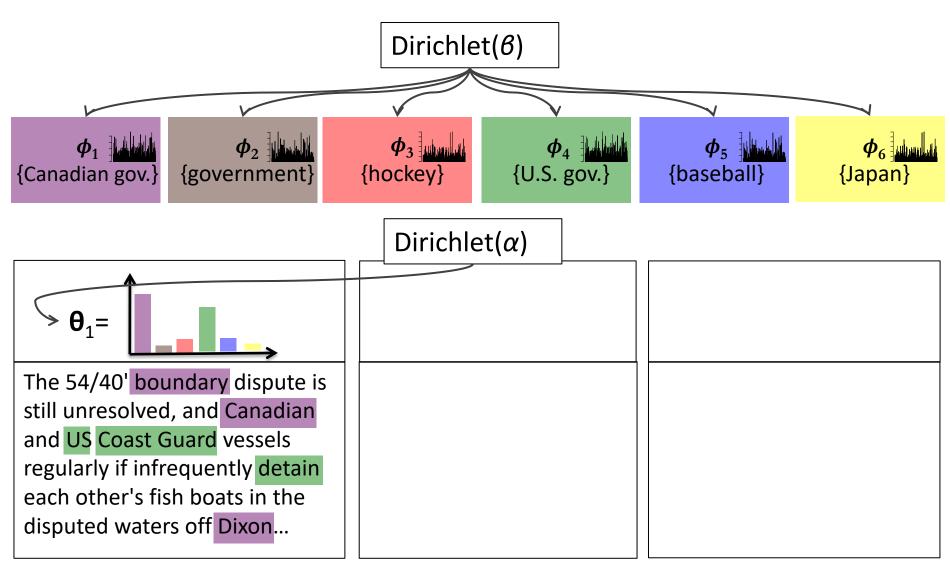
- A topic is visualized as its high probability words.
- A pedagogical label is used to identify the topic.

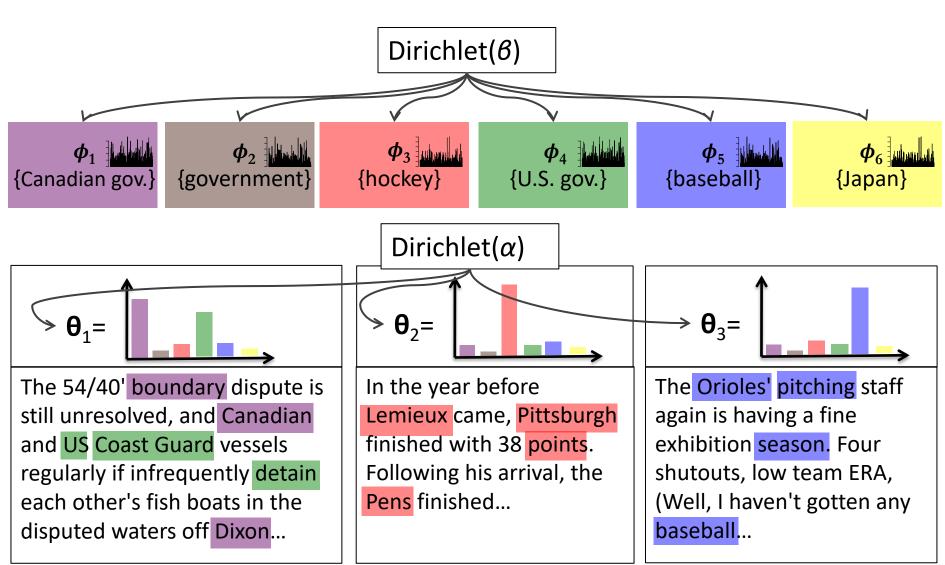


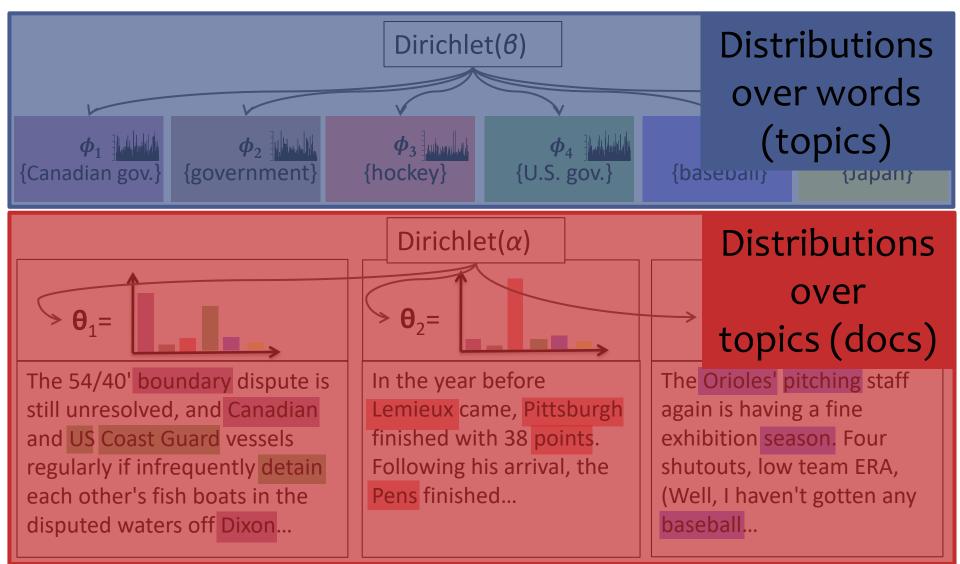


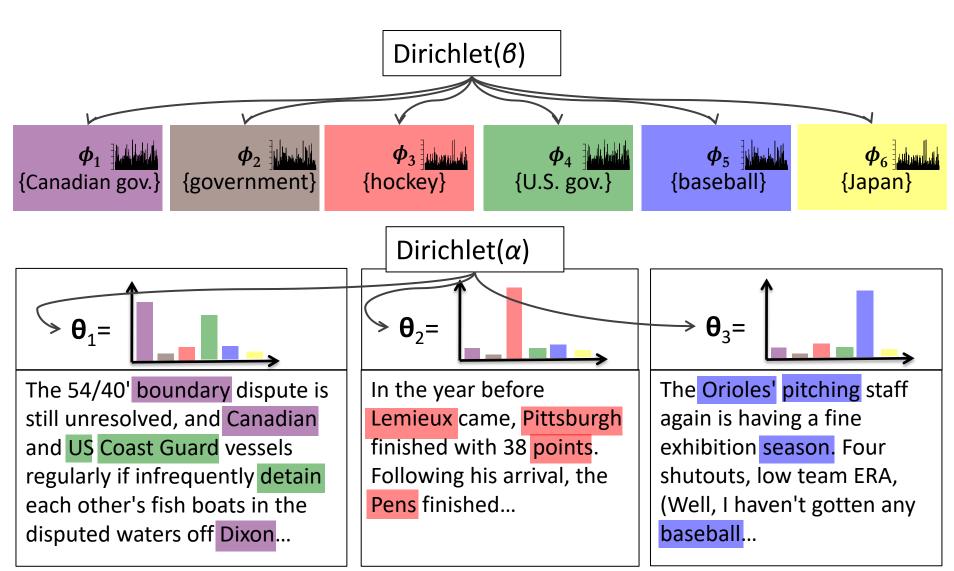












Inference and learning start with only the data

Dirichlet()

Dirichlet()



$$\phi_2 =$$

$$\phi_3 =$$

$$\phi_4 =$$

$$\phi_5 =$$

$$\phi_6$$
 =

The 54/40' boundary dispute is still unresolved, and Canadian and US Coast Guard vessels regularly if infrequently detain each other's fish boats in the disputed waters off Dixon...

In the year before Lemieux came, Pittsburgh finished with 38 points. Following his arrival, the Pens finished...

$$\rightarrow$$
 θ_3 =

The Orioles' itching staff again is having a fine exhibition season. Four shutouts, low team ERA, (Well, I haven't gotten any baseball...

Questions:

 Is this a believable story for the generation of a corpus of documents?

Why might it work well anyway?

Why does LDA "work"?

- LDA trades off two goals.
 - 1 For each document, allocate its words to as few topics as possible.
 - 2 For each topic, assign high probability to as few terms as possible.
- These goals are at odds.
 - Putting a document in a single topic makes #2 hard:
 All of its words must have probability under that topic.
 - Putting very few words in each topic makes #1 hard:
 To cover a document's words, it must assign many topics to it.
- Trading off these goals finds groups of tightly co-occurring words.

How does this relate to my other favorite model for capturing low-dimensional representations of a corpus?

- Builds on latent semantic analysis (Deerwester et al., 1990; Hofmann, 1999)
- It is a mixed-membership model (Erosheva, 2004).
- It relates to PCA and matrix factorization (Jakulin and Buntine, 2002)
- Was independently invented for genetics (Pritchard et al., 2000)

Outline

- Applications of Topic Modeling
- Review: Latent Dirichlet Allocation (LDA)
 - 1. Beta-Bernoulli
 - 2. Dirichlet-Multinomial
 - 3. Dirichlet-Multinomial Mixture Model
 - 4. LDA
- Contrast of methods for Inference / Learning
 - Exact inference
 - EM
 - Monte Carlo EM
 - Gibbs sampler
 - Collapsed Gibbs sampler
- Extensions of LDA
 - Correlated topic models
 - Dynamic topic models
 - Polylingual topic models
 - Supervised LDA

Unsupervised Learning

Three learning paradigms:

Maximum likelihood

$$\arg \max_{\theta} p(X|\theta)$$

1. Maximum a posteriori (MAP)

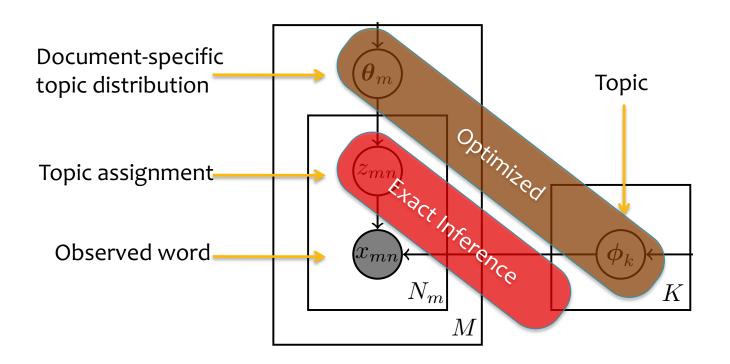
$$\arg \max_{\theta} p(\theta|X) \propto p(X|\theta)p(\theta)$$

Bayesian approach

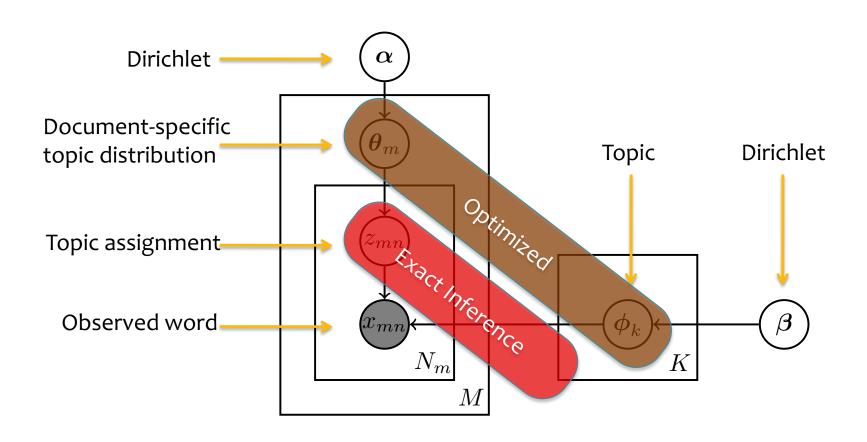
Estimate the posterior:

$$p(\theta|X) = \dots$$

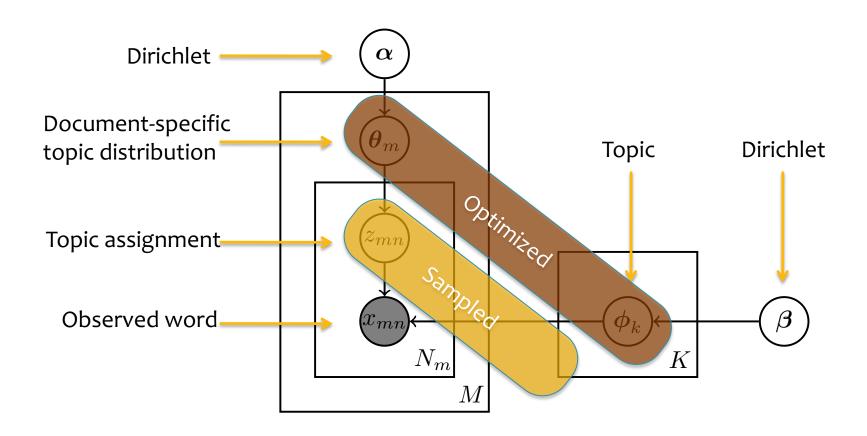
• Standard EM (Maximum Likelihood)



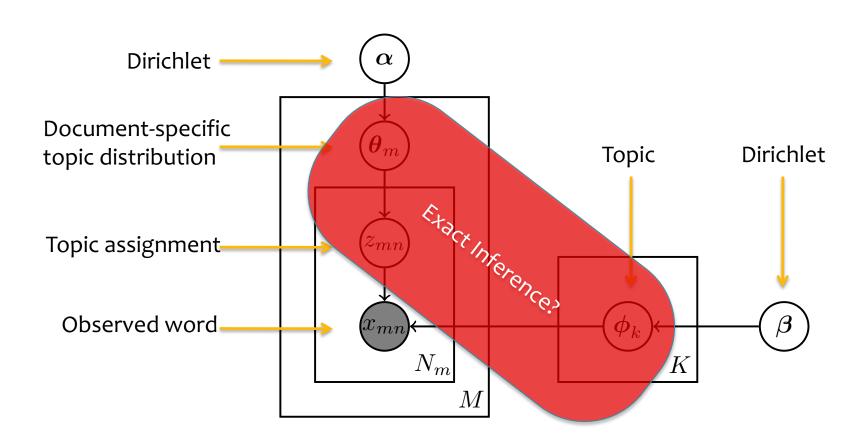
Standard EM (MAP)



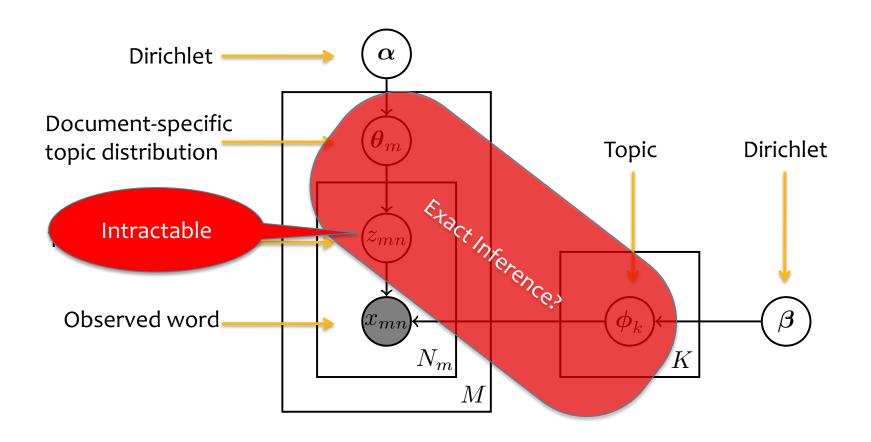
Monte Carlo EM



Bayesian Approach



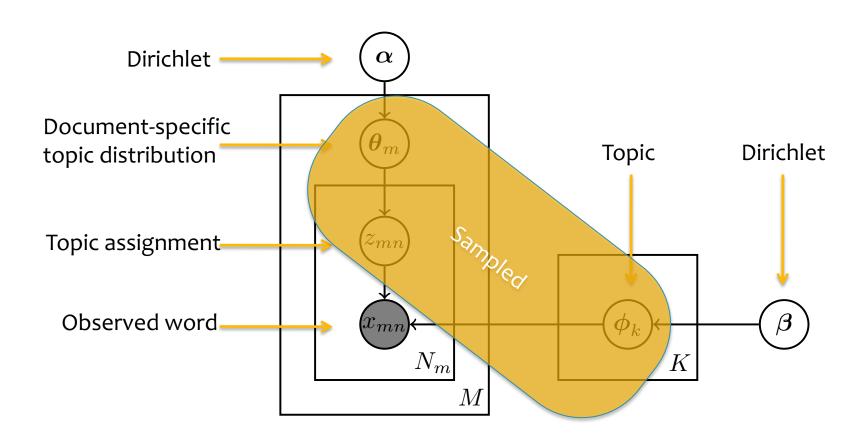
Bayesian Approach



Exact Inference in LDA

- Exactly computing the posterior is intractable in LDA
 - Junction tree algorithm: exact inference in general graphical models
 - 1. "moralization" converts directed to undirected
 - 2. "triangulation" breaks 4-cycles by adding edges
 - 3. Cliques arranged into a junction tree
 - Time complexity is exponential in size of cliques
 - LDA cliques will be large (at least O(# topics)), so complexity is O(2^{# topics})
- Exact MAP inference in LDA is NP-hard for a large number of topics (Sontag & Roy, 2011)

Explicit Gibbs Sampler



Collapsed Gibbs Sampler

