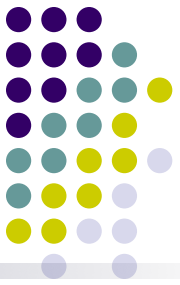


Loopy Belief Propagation

Kayhan Batmanghelich



Inference Problems

- Compute the likelihood of observed data
- Compute the marginal distribution $p(x_A)$ over a particular subset of nodes $A \subset V$
- Compute the conditional distribution $p(x_A|x_B)$ for disjoint subsets A and B
- Compute a mode of the density $\hat{x} = \arg \max_{x \in \mathcal{X}^m} p(x)$
- Methods we have

Brute force

Elimination



Message Passing

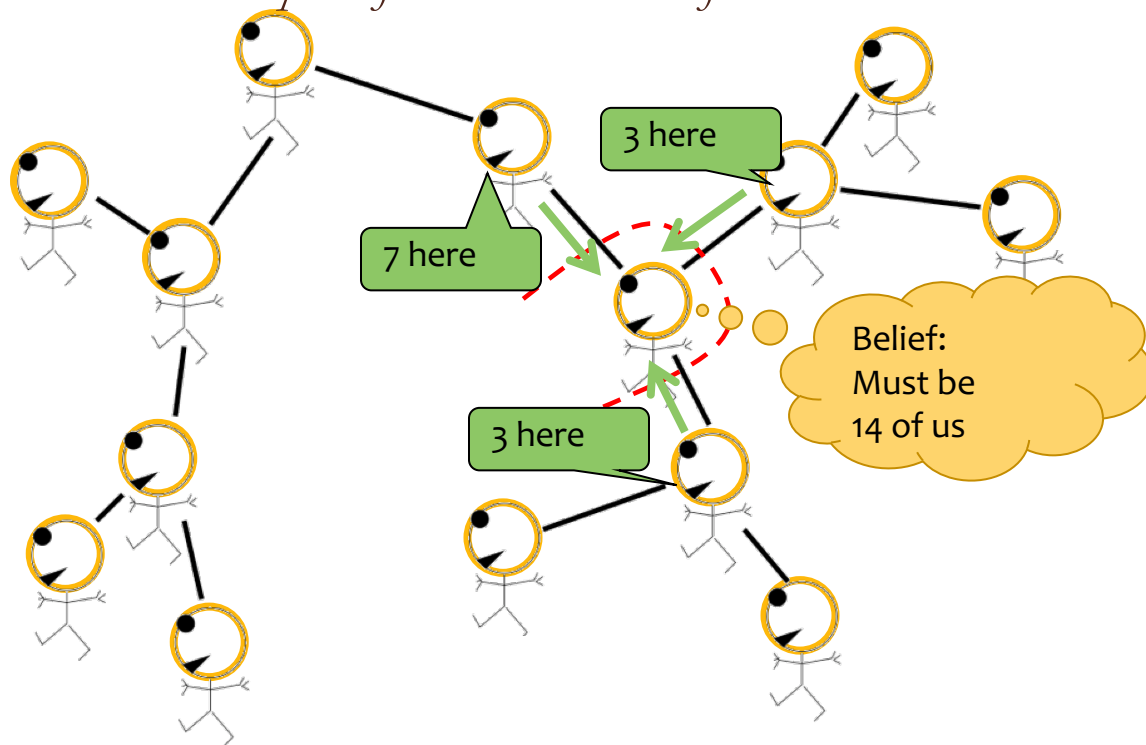
(Forward-backward , Max-product
/BP, Junction Tree)

Individual computations independent

Sharing intermediate terms

Great Ideas in ML: Message Passing

Each soldier receives reports from all branches of tree

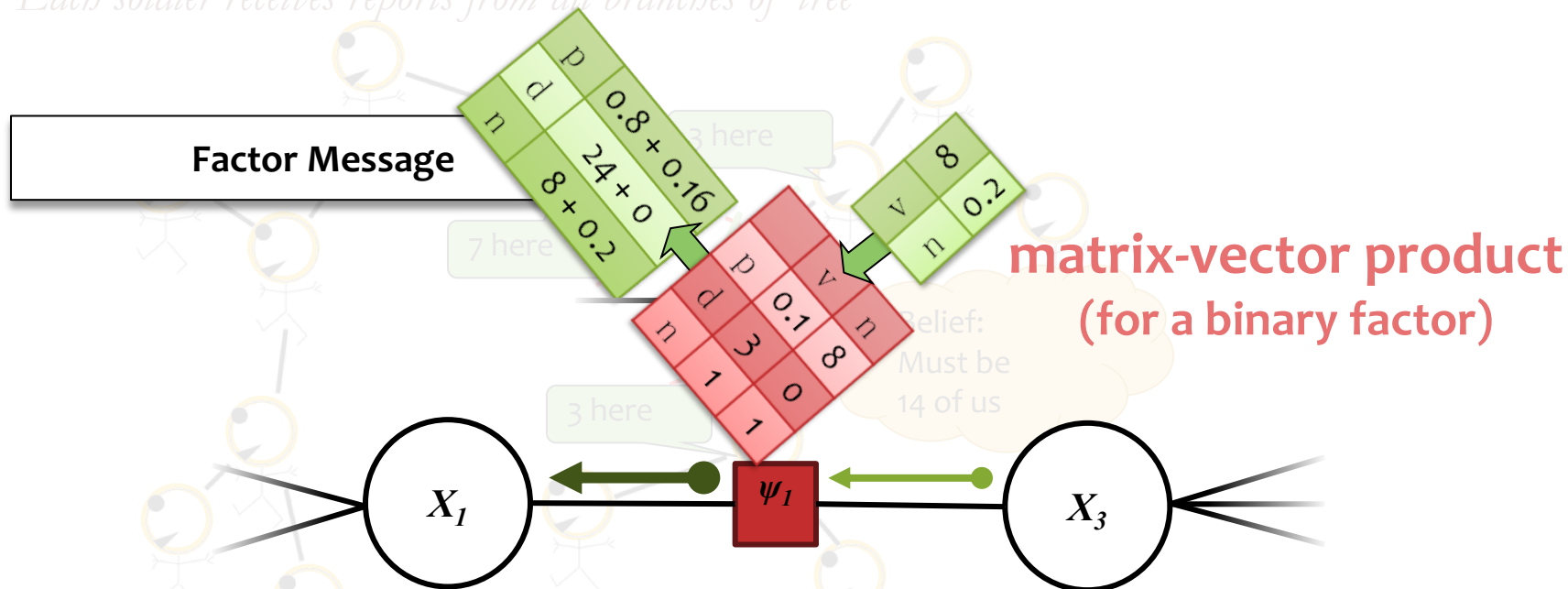


Slides adapted from
Matt Gormley
(2016)

adapted from MacKay (2003) textbook

Sum-Product Belief Propagation

Each soldier receives reports from all branches of tree



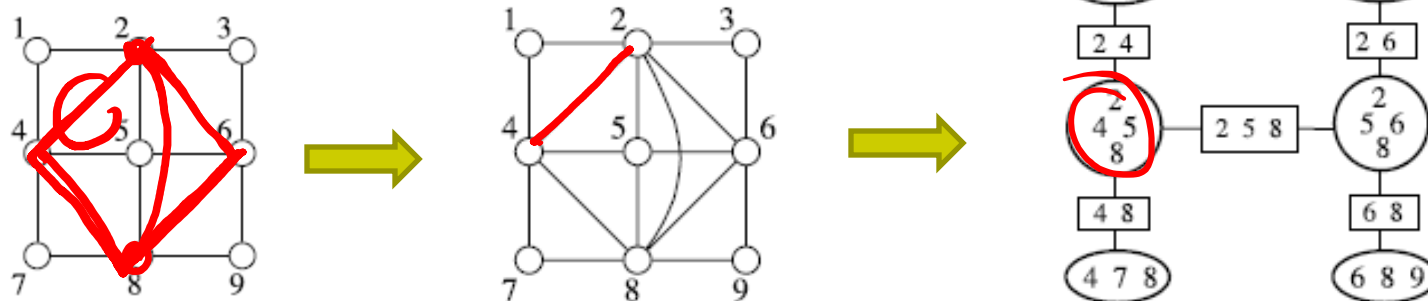
$$\mu_{\alpha \rightarrow i}(x_i) = \sum_{\mathbf{x}_{\alpha} : \mathbf{x}_{\alpha}[i] = x_i} \psi_{\alpha}(\mathbf{x}_{\alpha}) \prod_{j \in \mathcal{N}(\alpha) \setminus i} \mu_{j \rightarrow \alpha}(\mathbf{x}_{\alpha}[i])$$

adapted from (2016)

Junction Tree Revisited



- General Algorithm on Graphs with Cycles



- Steps:

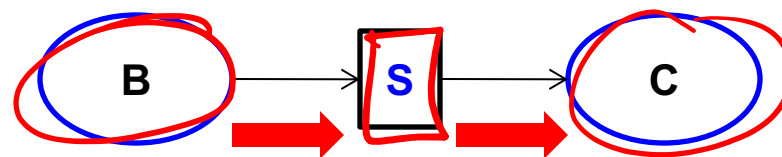
=> **Triangularization**

=> **Construct JTs**

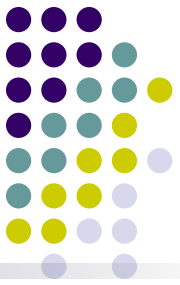
=> **Message Passing on Clique Trees**

$$\tilde{\phi}_S(x_S) \leftarrow \sum_{x_{B \setminus S}} \phi_B(x_B)$$

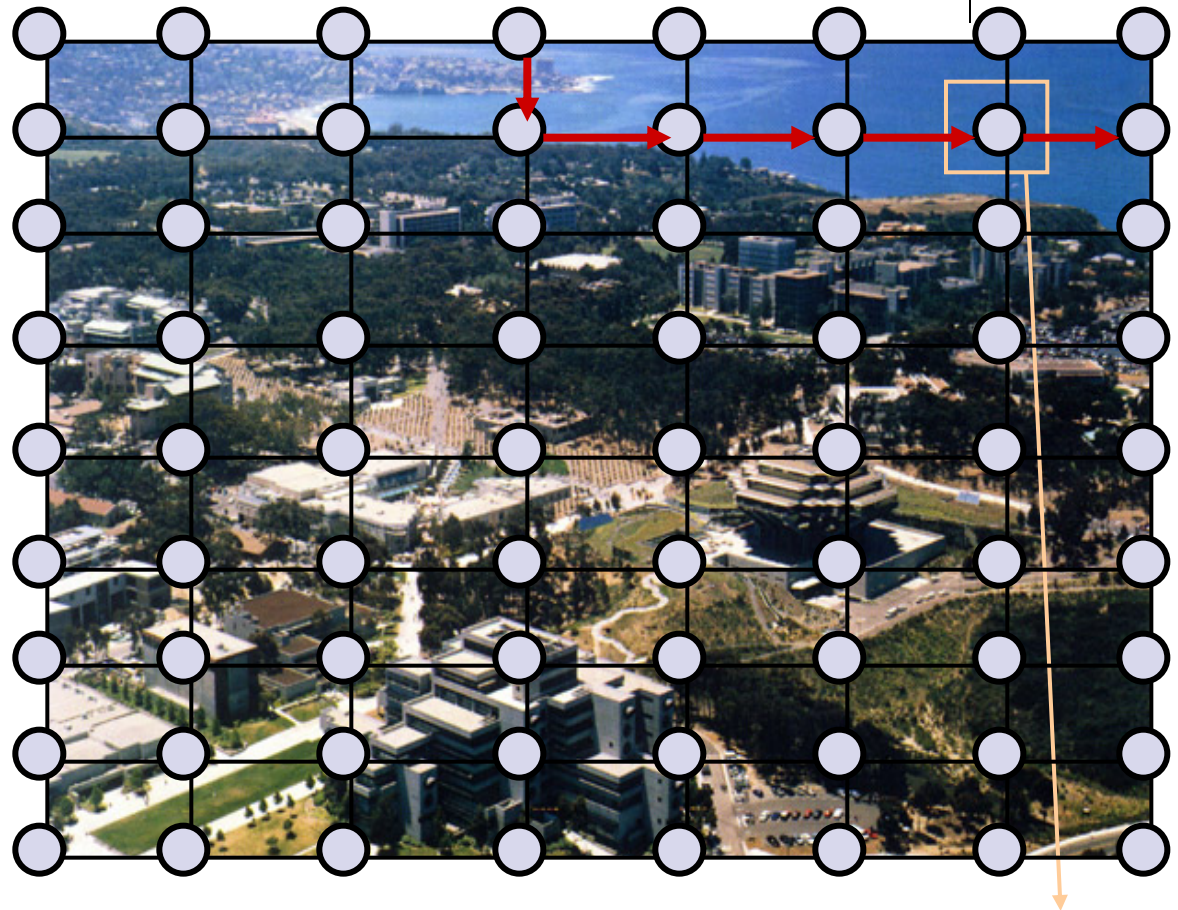
$$\phi_C(x_C) \leftarrow \frac{\tilde{\phi}_S(x_S)}{\phi_S(x_S)} \phi_C(x_C)$$



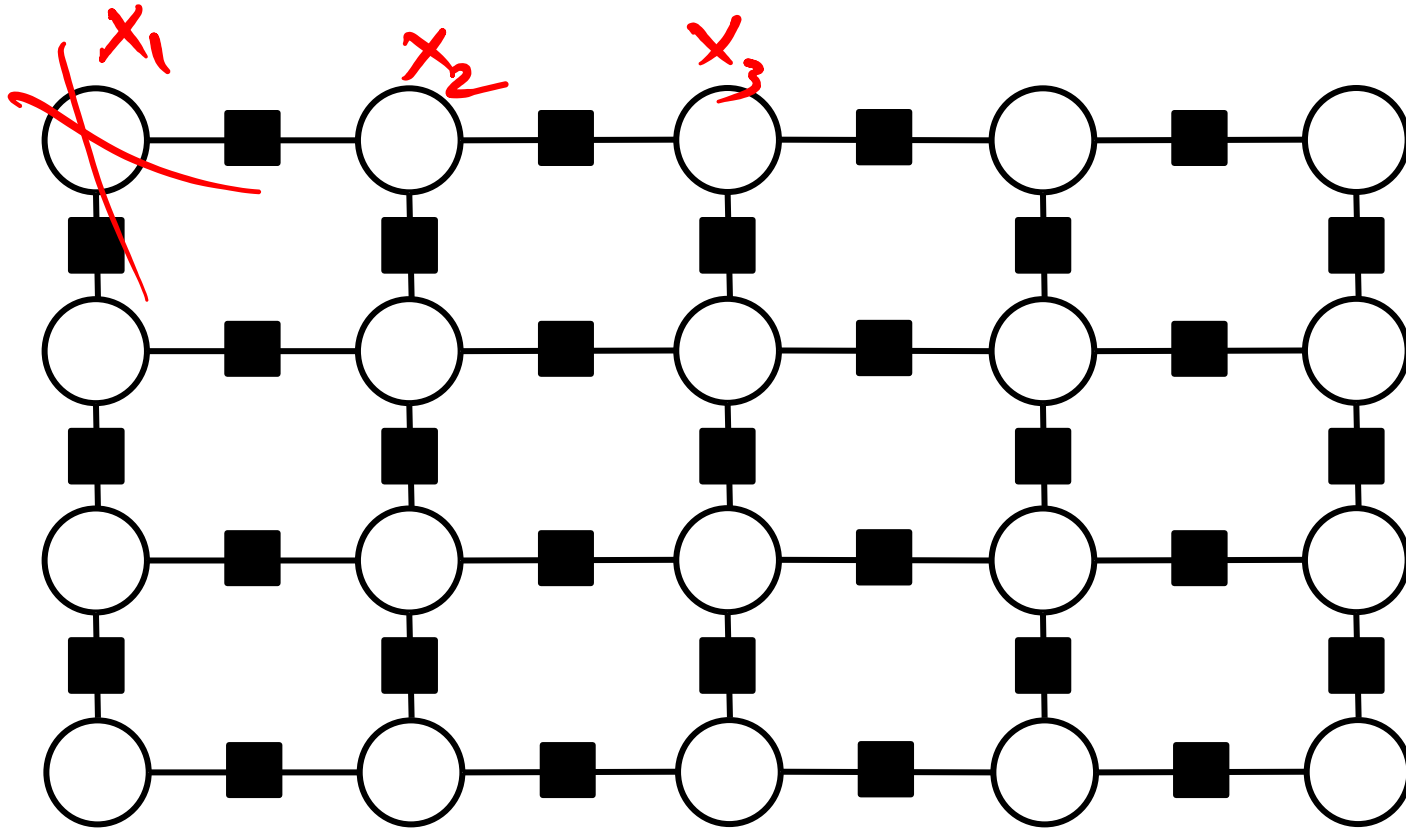
An Ising model on 2-D image



- Nodes encode hidden information (patch-identity).
- They receive local information from the image (brightness, color).
- Information is propagated through the graph over its edges.
- Edges encode 'compatibility' between nodes.

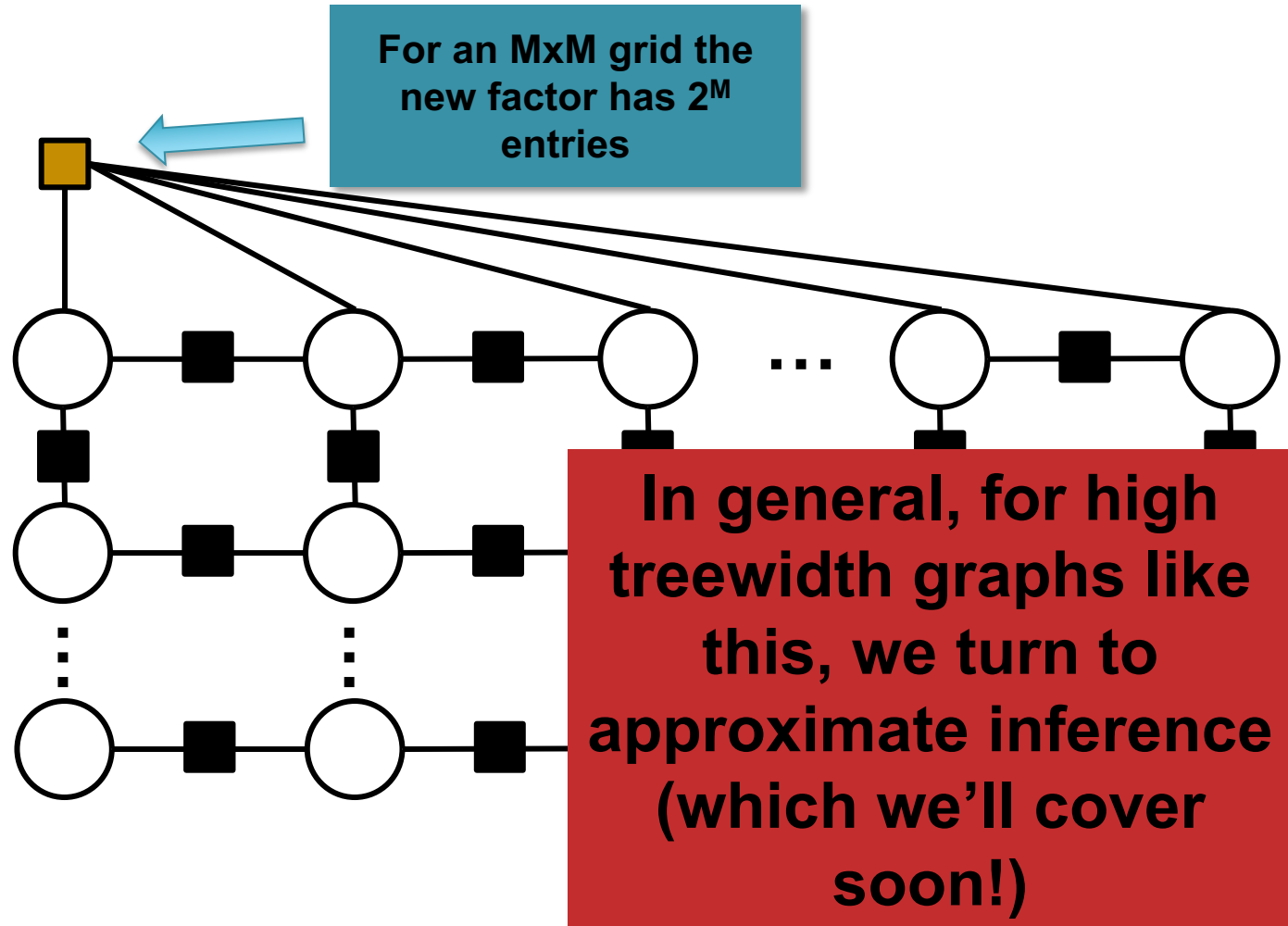


Why Approximate Inference?



$$p(X) = \frac{1}{Z} \exp\left\{ \sum_{i < j} \theta_{ij} \underline{x_i x_j} + \sum_i \theta_{i0} \underline{x_i} \right\}$$

Why Approximate Inference?





Approaches to inference

• Exact inference algorithms

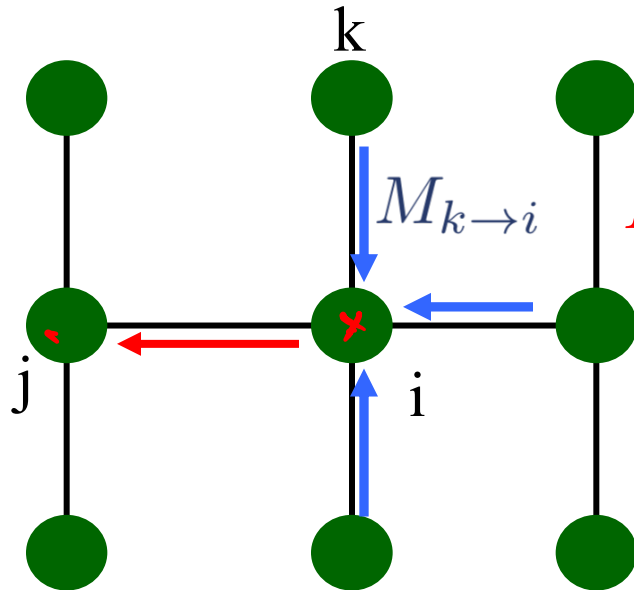
- The elimination algorithm
- Message-passing algorithm (sum-product, belief propagation)
- The junction tree algorithms

• Approximate inference techniques

- Variational algorithms
 - Loopy belief propagation
 - Mean field approximation
- Stochastic simulation / sampling methods
- Markov chain Monte Carlo methods

Recap of Belief Propagation

Recap: Belief Propagation



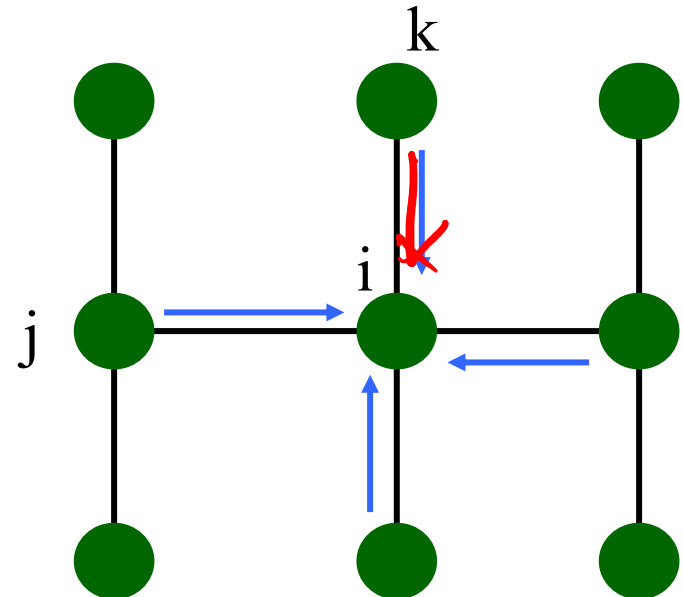
$$M_{k \rightarrow i}(x_j) \propto \sum_{x_i}$$

$$\psi_{ij}(x_i, x_j) \psi_i(x_i) \prod_k M_{k \rightarrow i}(x_i)$$

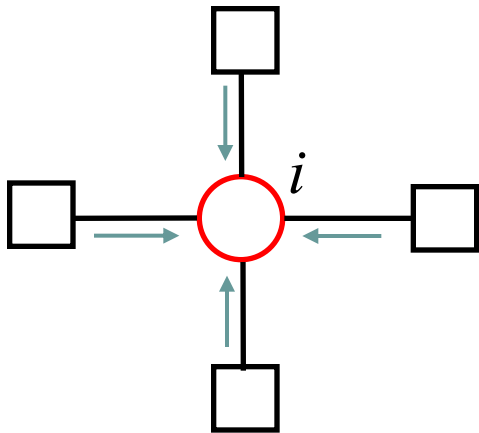
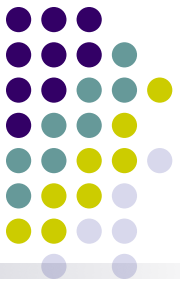
Handwritten annotations: "bin" and "kni" are circled in red above the equation. "Interactions" is written in blue below $\psi_{ij}(x_i, x_j)$. "External evidence" is written in blue below $\prod_k M_{k \rightarrow i}(x_i)$.

$$b_i(x_i) \propto \psi(x_i) \prod_k M_{k \rightarrow i}(x_i)$$

Handwritten annotation: $\psi(x_i)$ is circled in red.



Beliefs and messages in FG

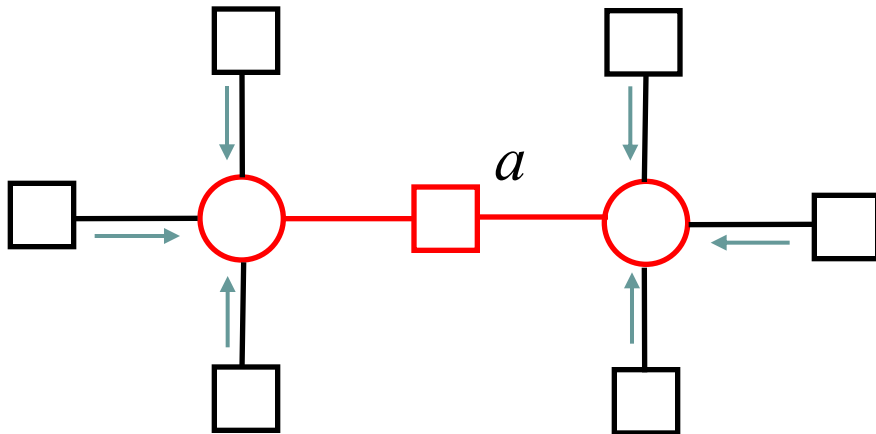


$$m_{i \rightarrow a}(x_i) = \prod_{c \in N(i) \setminus a} m_{c \rightarrow i}(x_i)$$

$$\underline{b_i(x_i)} \propto \prod_{a \in N(i)} m_{a \rightarrow i}(x_i)$$

“beliefs”

“messages”



$$\underline{b_a(X_a)} \propto \underline{f_a(X_a)} \prod_{i \in N(a)} m_{i \rightarrow a}(x_i)$$

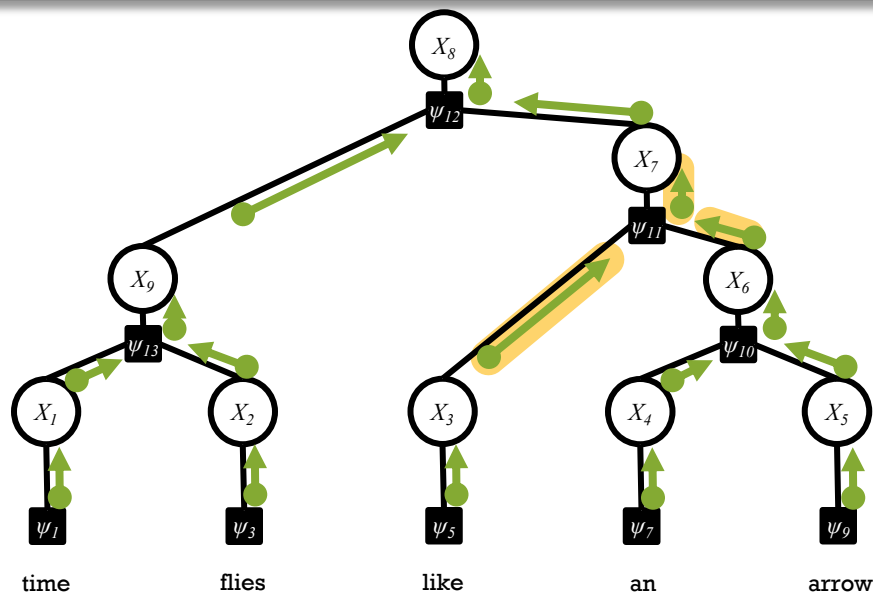
$$m_{a \rightarrow i}(x_i) = \sum_{\underline{X_a \setminus x_i}} \underline{f_a(X_a)} \prod_{j \in N(a) \setminus i} m_{j \rightarrow a}(x_j)$$

(Acyclic) Belief Propagation

In a factor graph with no cycles:

1. Pick any node to serve as the **root**.
2. Send messages from the **leaves** to the **root**.
3. Send messages from the **root** to the **leaves**.

A node computes an outgoing message along an edge only after it has received incoming messages along all its other edges.

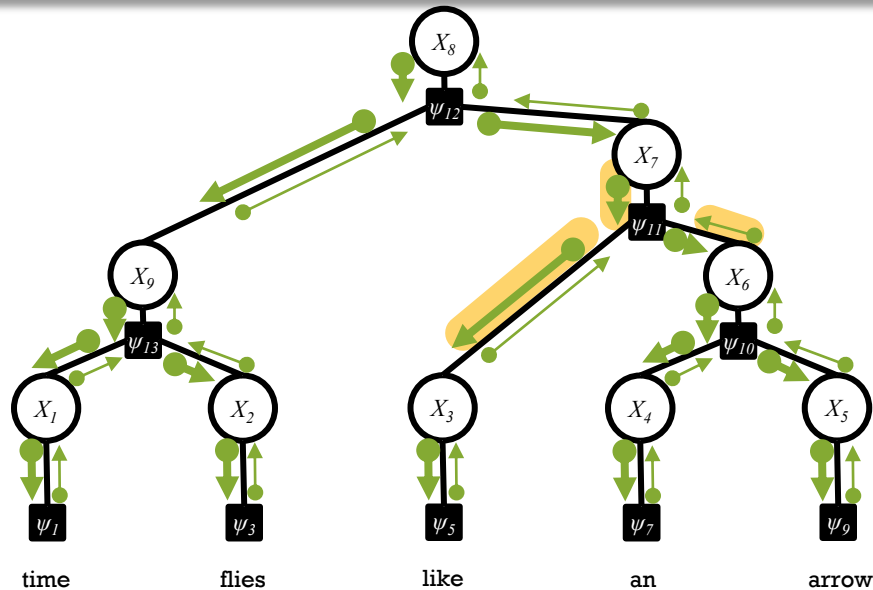


(Acyclic) Belief Propagation

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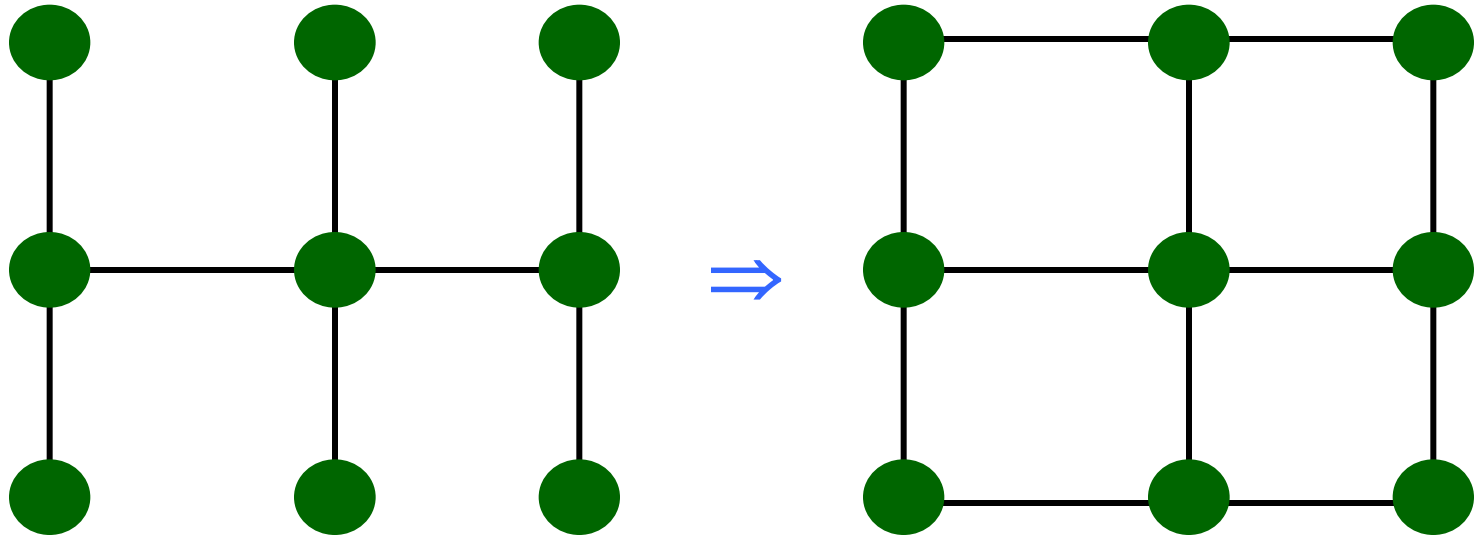
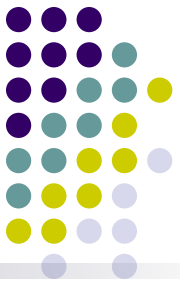
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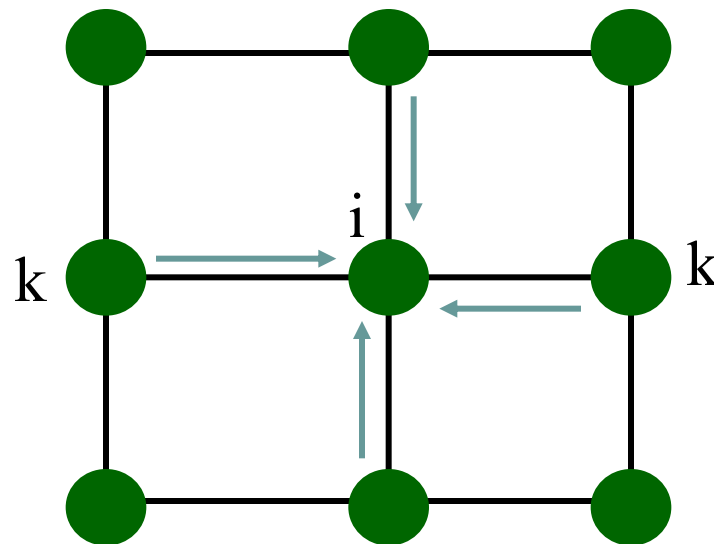
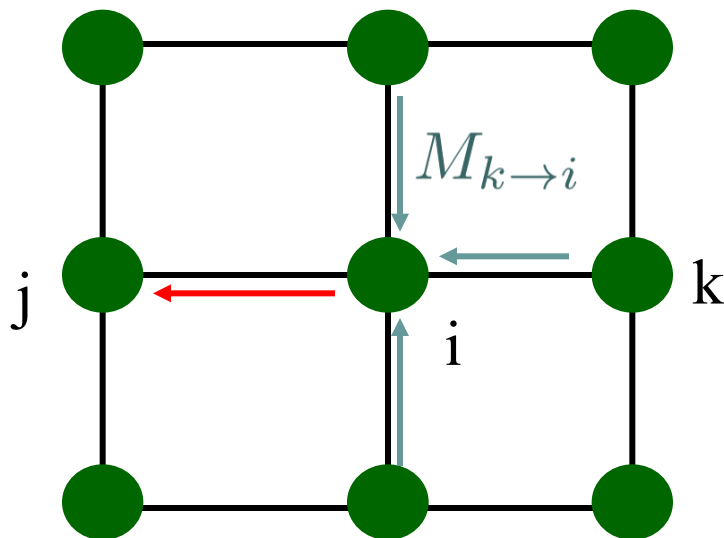
Slides adapted from
Matt Gormley
(2016)

What if there is a loop?

What if the graph is loopy?



Belief Propagation on loopy graphs

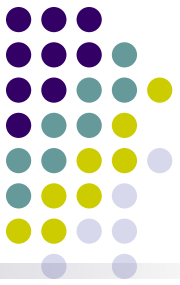


- BP Message-update Rules

$$M_{i \rightarrow j}(x_j) \propto \sum_{x_i} \underbrace{\psi_{ij}(x_i, x_j)}_{\text{Compatibilities (interactions)}} \underbrace{\psi_i(x_i)}_{\text{external evidence}} \prod_k M_{k \rightarrow i}(x_i)$$

$$b_i(x_i) \propto \psi_i(x_i) \prod_k M_k(x_k)$$

- May not converge or converge to a wrong solution



Loopy Belief Propagation

- A fixed point iteration procedure that tries to minimize F_{bethe}
- Start with random initialization of messages and beliefs
- While not converged do

$$b_i(x_i) \propto \prod_{a \in N(i)} m_{a \rightarrow i}(x_i) \qquad b_a(X_a) \propto f_a(X_a) \prod_{i \in N(a)} m_{i \rightarrow a}(x_i)$$

$$m_{i \rightarrow a}^{\text{new}}(x_i) = \prod_{c \in N(i) \setminus a} m_{c \rightarrow i}(x_i) \qquad m_{a \rightarrow i}^{\text{new}}(x_i) = \sum_{X_a \setminus x_i} f_a(X_a) \prod_{j \in N(a) \setminus i} m_{j \rightarrow a}(x_j)$$

- At convergence, stationarity properties are guaranteed
- However, not guaranteed to converge!

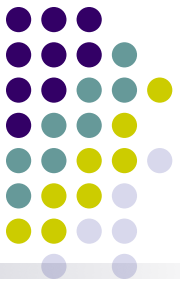


Loopy Belief Propagation

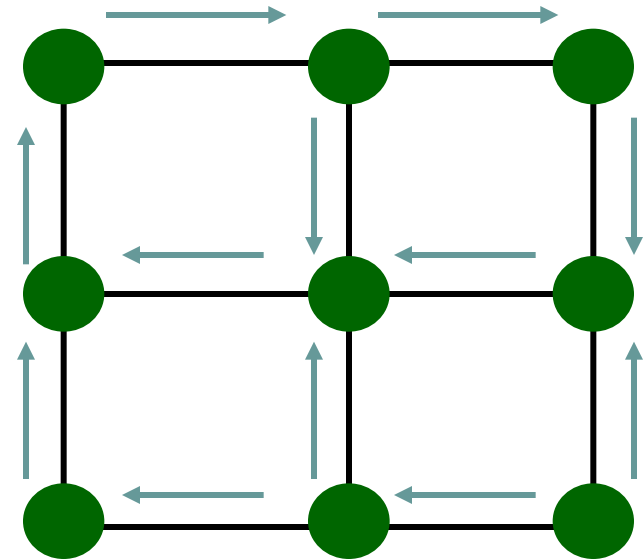
- If BP is used on graphs with loops, messages **may** circulate indefinitely
- But let's **run it anyway** and hope for the best ... 😊
- How to stop it?
 - Stop after fixed # of iterations
 - Stop when no significant change in beliefs
 - If solution is not oscillatory but converges, it usually is a good approximation

[Loopy-belief Propagation for Approximate Inference: An Empirical Study](#)
Kevin Murphy, Yair Weiss, and Michael Jordan.
UAI '99 (Uncertainty in AI).]

So what is going on?



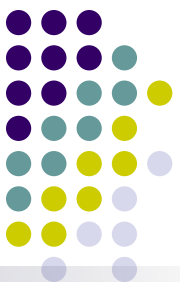
- Is it a dirty hack that you bet your luck?



$$P(x_A | \text{Data})$$

approximate $q(x_A) = 42$

How to measure how close we to the correct answer?



$$D(Q_1, Q_2) = KL(Q_1 || Q_2) + KL(Q_2 || Q_1)$$

Approximate Inference

- Let us call the actual distribution P

$$P(X) = 1/Z \prod_{f_a \in F} f_a(X_a)$$

- We wish to find a distribution Q such that Q is a “good” approximation to P
- Recall the definition of KL-divergence

$$KL(Q_1 || Q_2) = \sum_X Q_1(X) \log\left(\frac{Q_1(X)}{Q_2(X)}\right)$$

- $KL(Q_1 || Q_2) \geq 0$ ✓
- $KL(Q_1 || Q_2) = 0$ iff $Q_1 = Q_2$
- We can therefore use KL as a scoring function to decide a good Q
- But, $KL(Q_1 || Q_2) \neq KL(Q_2 || Q_1)$

$$D(Q_1, Q_2) \leq$$

$$D(Q_1, Q_3)$$

$$+ D(Q_3, Q_2)$$

Which KL?



- Computing $KL(P||Q)$ requires inference!
- But $KL(Q||P)$ can be computed without performing inference on P

$$\begin{aligned} KL(Q || P) &= \sum_x Q(X) \log \left(\frac{Q(X)}{P(X)} \right) \\ &= \sum_x Q(X) \log Q(X) - \sum_x Q(X) \log P(X) = \mathbb{E}[\log Q(X)] \\ &= -H_Q(X) - E_Q \log P(X) \end{aligned}$$

$\rightarrow \mathbb{E}[\log P(X)]$

- Using $P(X) = 1/Z \prod_{f_a \in F} f_a(X_a)$

$$\begin{aligned} KL(Q || P) &= -H_Q(X) - E_Q \log \left(1/Z \prod_{f_a \in F} f_a(X_a) \right) \\ &= -H_Q(X) - \log 1/Z - \sum_{f_a \in F} E_Q \log f_a(X_a) \end{aligned}$$

Optimization function



$$\begin{aligned} & \phi(x) \\ & Q \\ & KL(Q \parallel P) = -H_Q(X) - \underbrace{\sum_{f_a \in F} E_Q \log f_a(X_a)}_{F(P, Q)} + \log Z \\ & Q = P \end{aligned}$$

- We will call $F(P, Q)$ the “Free energy” *
- $F(P, P) = ?$

- $F(P, Q) \geq F(P, P)$

The Energy Functional



- Let us look at the functional

$$F(P, Q) = -H_Q(X) - \sum_{f_a \in F} E_Q \log f_a(X_a)$$

- $\sum_{f_a \in F} E_Q \log f_a(X_a)$ can be computed if we have marginals over each f_a
- $H_Q = -\sum_X Q(X) \log Q(X)$ is **harder**! Requires summation over all possible values
- Computing F , is therefore hard in general.
- Our goal is to:

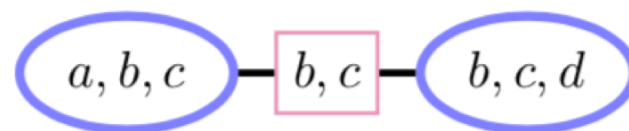
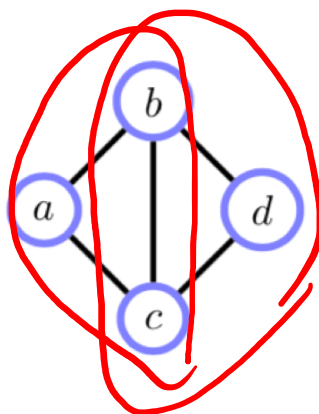
$$Q^* = \arg \max_{Q \in \mathcal{Q}} F(P, Q)$$

Can we approximate it?

Can we suggest an easy family?

Work out a simple case

Do you remember this from lecture 6 ?



$$p(a, b, c, d) = \frac{\phi(a, b, c)\phi(b, c, d)}{Z} = \frac{p(a, b, c)p(b, c, d)}{p(c, b)}$$

[illegible]

$$F(P, Q) = -H_Q(X) - \sum_{f_a \in F} E_Q \log f_a(X_a)$$

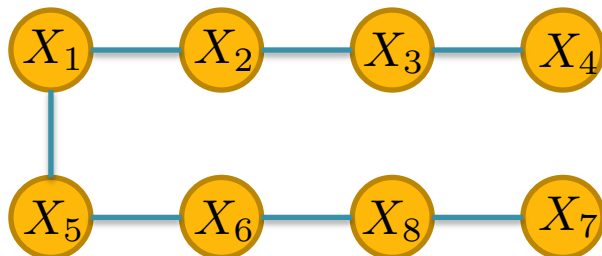
$$P(X_3, X_4) P(X_2, X_3) P(X_1, X_2) \dots$$

$$P(X_3) P(X_2) \dots$$

$$H(X_1, \dots, X_8) = - \sum_{a \in \text{num}} \mathbb{E}[\log p(X_a)] + \sum_{i \in \text{den}} \mathbb{E}[\log p(x_i)]$$

$$F(X_1, \dots, X_8) = - \sum_{a \in \text{num}} \mathbb{E}[\log \frac{p(X_a)}{f(X_a)}] + \sum_{i \in \text{den}} \mathbb{E}[\log \frac{p(X_i)}{f(X_i)}]$$

For a general tree



$$F(P, Q) = -H_Q(X) - \sum_{f_a \in F} E_Q \log f_a(X_a)$$

- The probability can be written as: $b(\mathbf{x}) = \prod_a b_a(\mathbf{x}_a) \prod_i b_i(\mathbf{x}_i)^{1-d_i}$

$$H_{tree} = - \sum_a \sum_{\mathbf{x}_a} b_a(\mathbf{x}_a) \ln b_a(\mathbf{x}_a) - \sum_i (d_i - 1) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \ln b_i(\mathbf{x}_i)$$

num
den

$$F_{Tree} = \sum_a \sum_{\mathbf{x}_a} b_a(\mathbf{x}_a) \ln \frac{b_a(\mathbf{x}_a)}{f_a(\mathbf{x}_a)} + \sum_i (1 - d_i) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \ln b_i(\mathbf{x}_i)$$

↑
Degree of the node

- involves summation over **edges** and **vertices** and is therefore easy to compute

$$= F_{12} + F_{23} + \dots + F_{67} + F_{78} - F_1 - F_5 - F_2 - F_6 - F_3 - F_7$$

Let's extend it to a general graph

Bethe Approximation to Gibbs Free Energy



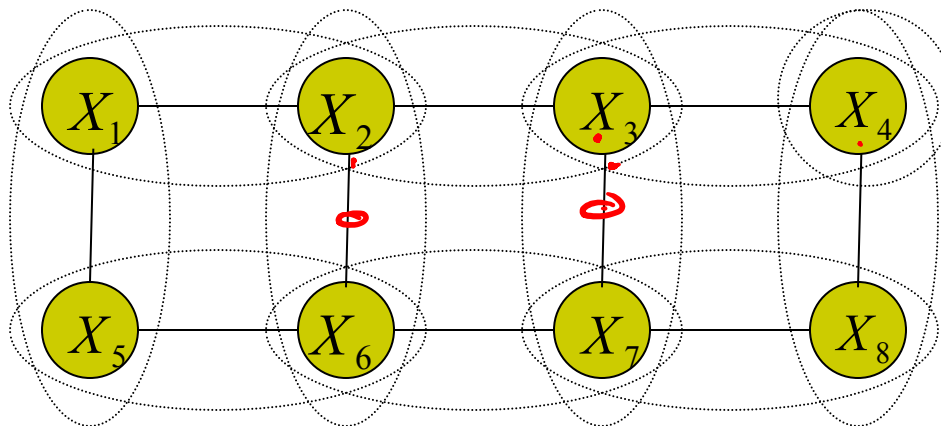
$F(Q,P)$ \hat{F}

- For a general graph, choose $\hat{F}(P,Q) = F_{Bethe}$

$$H_{Bethe} = - \sum_a \sum_{\mathbf{x}_a} b_a(\mathbf{x}_a) \ln b_a(\mathbf{x}_a) + \sum_i (d_i - 1) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \ln b_i(\mathbf{x}_i)$$

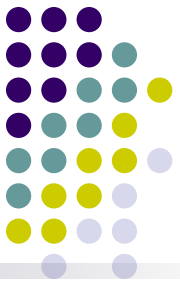
$$F_{Bethe} = \sum_a \sum_{\mathbf{x}_a} b_a(\mathbf{x}_a) \ln \frac{b_a(\mathbf{x}_a)}{f_a(\mathbf{x}_a)} + \sum_i (1 - d_i) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \ln b_i(\mathbf{x}_i) = -\langle f_a(\mathbf{x}_a) \rangle - H_{Bethe}$$

- Called “Bethe approximation” after the physicist Hans Bethe



$$F_{Bethe} = F_{12} + F_{23} + \dots + F_{67} + F_{78} - F_1 - F_5 - 2F_2 - 2F_6 \dots - F_8$$

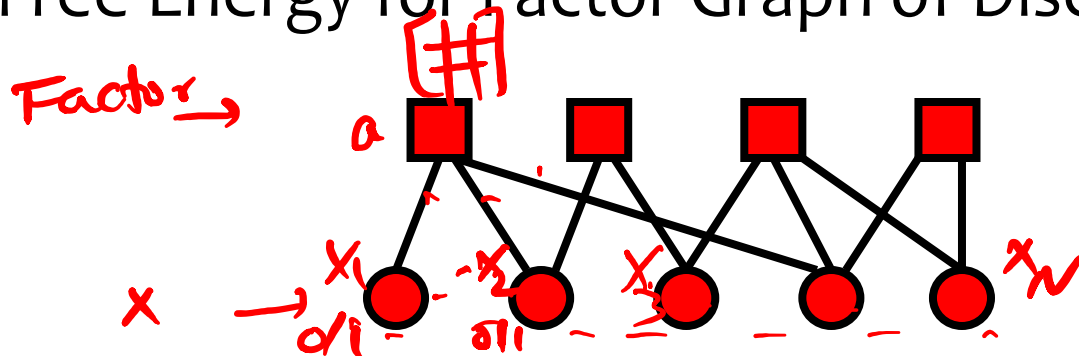
- Equal to the exact Gibbs free energy when the factor graph is a tree
- In general, H_{Bethe} is **not** the same as the H of a tree



Bethe Approximation

- Pros:
 - Easy to compute, since entropy term involves sum over pairwise and single variables
- Cons:
 - $\hat{F}(P, Q) = F_{\text{bethe}}$ **may or may not** be well connected to $F(P, Q)$
 - It could, in general, be **greater**, **equal** or **less** than $F(P, Q)$!!
- Optimize each $b(\mathbf{x}_a)$'s.
 - For discrete belief, constrained opt. with *Lagrangian* multiplier
 - For continuous belief, not yet a general formula
 - Not always converge

Bethe Free Energy for Factor Graph of Discrete RVs



$$F_{\text{Bethe}} = \sum_a \sum_{\mathbf{x}_a} \boxed{b_a(\mathbf{x}_a)} \ln \frac{b_a(\mathbf{x}_a)}{f_a(\mathbf{x}_a)} + \sum_i (1 - d_i) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \ln b_i(\mathbf{x}_i)$$

$$H_{\text{Bethe}} = - \sum_a \sum_{\mathbf{x}_a} b_a(\mathbf{x}_a) \ln b_a(\mathbf{x}_a) + \sum_i (d_i - 1) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \ln b_i(\mathbf{x}_i)$$

$$F_{\text{Bethe}} = - \sum_a \langle f_a(\mathbf{x}_a) \rangle - H_{\text{Bethe}}$$

How about optimizing this:

$$\min_{b_a(\mathbf{x}_a), b_i(\mathbf{x}_i)} F_{\text{Bethe}}$$

Subject to:

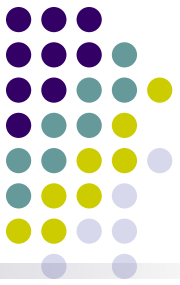
$$\sum_a b_a(\mathbf{x}_a) = 1 \quad \sum_i b_i(\mathbf{x}_i) = 1$$

$$b_i(\mathbf{x}_i) \geq 0$$

$$\sum_{a \sim j} b_a(\mathbf{x}_a) = b_j(\mathbf{x}_j)$$

$$b(x_{1,2})$$

$a=1,2$



$$b(x_a) = \exp(u)$$

Minimizing the Bethe Free Energy

- $$L = F_{\text{Bethe}} + \sum_i \gamma_i \{1 - \sum_{x_i} b_i(x_i)\} + \sum_a \sum_{i \in N(a)} \sum_{x_i} \lambda_{ai}(x_i) \left\{ b_i(x_i) - \sum_{X_a \setminus x_i} b_a(X_a) \right\}$$
- Set derivative to zero

Constrained Minimization of the Bethe Free Energy



$$L = F_{Bethe} + \sum_i \gamma_i \left\{ \sum_{x_i} b_i(x_i) - 1 \right\} \\ + \sum_a \sum_{i \in N(a)} \sum_{x_i} \lambda_{ai}(x_i) \left\{ \sum_{X_a \setminus x_i} b_a(X_a) - b_i(x_i) \right\}$$

$$\frac{\partial L}{\partial b_i(x_i)} = 0 \quad \Rightarrow \quad b_i(x_i) \propto \exp \left(\frac{1}{d_i - 1} \sum_{a \in N(i)} \lambda_{ai}(x_i) \right)$$

$$\frac{\partial L}{\partial b_a(X_a)} = 0 \quad \Rightarrow \quad b_a(X_a) \propto \exp \left(-E_a(X_a) + \sum_{i \in N(a)} \lambda_{ai}(x_i) \right)$$

Bethe = BP on FG

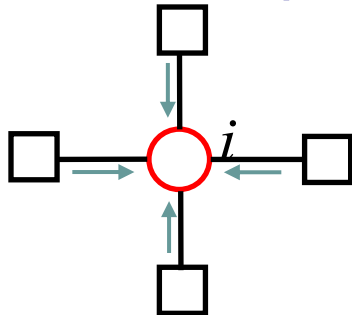


- We had:

$$b_i(x_i) \propto \exp\left(\frac{1}{d_i - 1} \sum_{a \in N(i)} \lambda_{ai}(x_i)\right) \quad b_a(X_a) \propto \exp\left(-\log f_a(X_a) + \sum_{i \in N(a)} \lambda_{ai}(x_i)\right)$$

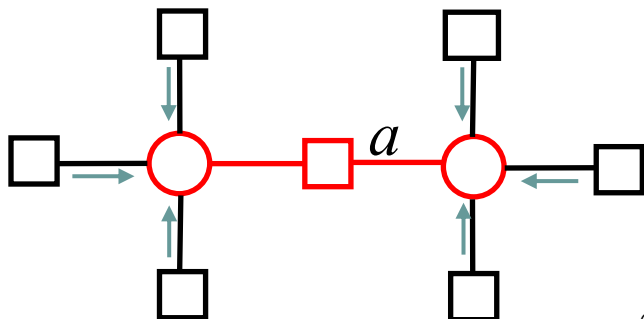
- Identify $\lambda_{ai}(x_i) = \log(m_{i \rightarrow a}(x_i)) = \log \prod_{b \in N(i) \neq a} m_{b \rightarrow i}(x_i)$

- to obtain BP equations:



$$b_i(x_i) \propto f_i(x_i) \prod_{a \in N(i)} m_{a \rightarrow i}(x_i)$$

↑ "beliefs"
 ↑ "messages"



$$b_a(X_a) \propto f_a(X_a) \prod_{i \in N(a)} \prod_{c \in N(i) \setminus a} m_{c \rightarrow i}(x_i)$$

The "belief" is the BP approximation of the marginal probability.

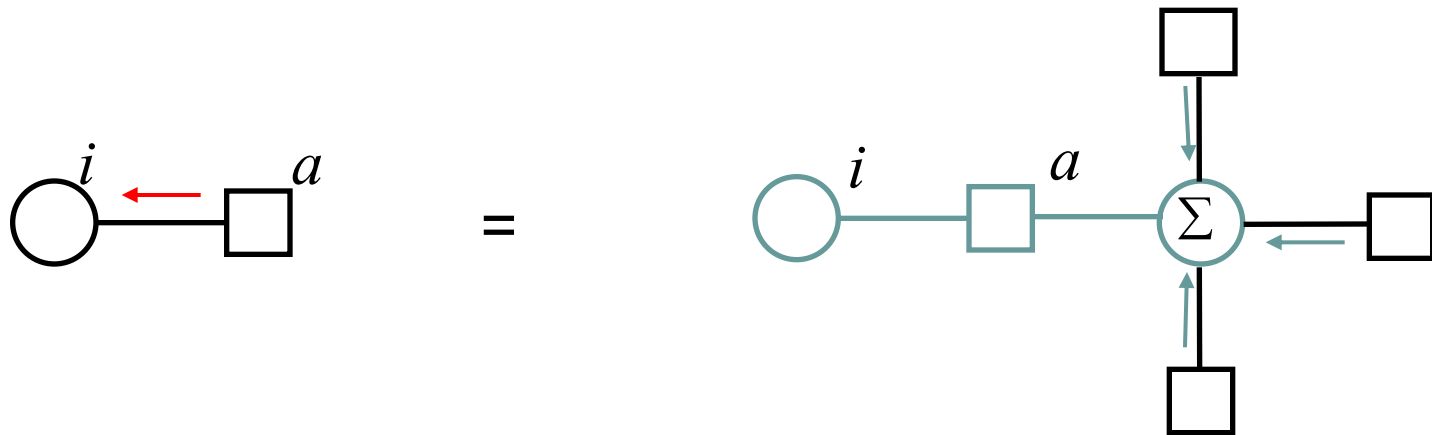


BP Message-update Rules

Using $b_{a \rightarrow i}(x_i) = \sum_{X_a \setminus x_i} b_a(X_a)$, we get

$$m_{a \rightarrow i}(x_i) = \sum_{X_a \setminus x_i} f_a(X_a) \prod_{j \in N(a) \setminus i} \prod_{b \in N(j) \setminus a} m_{b \rightarrow j}(x_j)$$

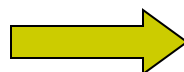
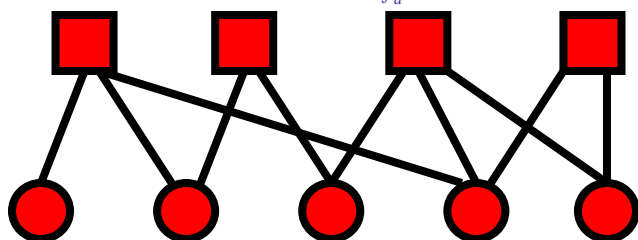
(A sum product algorithm)



Summary so far



$$P(X) = 1/Z \prod_{f_a \in F} f_a(X_a)$$



$$F(P, Q) = -H_Q(X) - \sum_{f_a \in F} E_Q \log f_a(X_a)$$

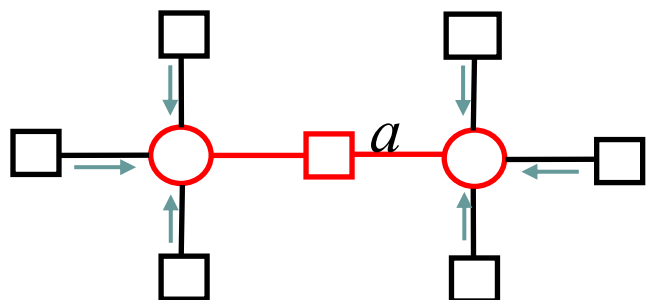


$$\hat{F}(P, Q) = \sum_a \sum_{\mathbf{x}_a} b_a(\mathbf{x}_a) \log \frac{f_a(\mathbf{x}_a)}{b_a(\mathbf{x}_a)} + \sum_i (1 - d_i) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \log b_i(\mathbf{x}_i)$$



$$b_a(X_a) \propto \exp \left(-\log f_a(X_a) + \sum_{i \in N(a)} \lambda_{ai}(x_i) \right)$$

$$b_i(x_i) \propto \exp \left(\frac{1}{d_i - 1} \sum_{a \in N(i)} \lambda_{ai}(x_i) \right)$$



The Theory Behind LBP

$$F(Q, P)$$



- For a distribution $p(X|\theta)$ associated with a complex graph, computing the marginal (or conditional) probability of arbitrary random variable(s) is intractable
- Variational methods
 - formulating probabilistic inference as an optimization problem:

$$q^* = \arg \min_{q \in \mathcal{S}} \{ F_{\text{Bethe}}(p, q) \}$$

$$F_{\text{Bethe}} = \sum_a \sum_{\mathbf{x}_a} b_a(\mathbf{x}_a) \ln \frac{b_a(\mathbf{x}_a)}{f_a(\mathbf{x}_a)} + \sum_i (1 - d_i) \sum_{\mathbf{x}_i} b_i(\mathbf{x}_i) \ln b_i(\mathbf{x}_i) = -\langle f_a(\mathbf{x}_a) \rangle - H_{\text{Bethe}}$$

Optimizing the marginal in the Bethe energy is **a** way to make q tractable !

$$Ax \geq b \quad x_i \in 0/1$$

$$X = (x_1, \dots, x_N)$$



The Theory Behind LBP

- But we do not optimize $q(\mathbf{X})$ explicitly, focus on the set of beliefs

- e.g., $b = \{b_{i,j} = \tau(x_i, x_j), b_i = \tau(x_i)\}$

$$P = \begin{bmatrix} P_{11} \\ \vdots \\ P_{NN} \end{bmatrix}$$

- Relax the optimization problem

- approximate objective:

$$H_q \approx F(b)$$

- relaxed feasible set:

$$\mathcal{M} \rightarrow \mathcal{M}_o \quad (\mathcal{M}_o \supseteq \mathcal{M})$$

$$b^* = \arg \min_{b \in \mathcal{M}_o} \{ \langle E \rangle_b + F(b) \}$$

- The loopy BP algorithm:

- a fixed point iteration procedure that tries to solve b^*

$$Ax \geq \begin{bmatrix} a_1 \\ \vdots \\ a_N \end{bmatrix} x$$

$a_2 x \geq 0$ $a_1 x \geq 0$



The Theory Behind LBP

- But we do not optimize $q(\mathbf{X})$ explicitly, focus on the set of beliefs
 - *e.g.*, $b = \{b_{i,j} = \tau(x_i, x_j), b_i = \tau(x_i)\}$
 - Relax the optimization problem
 - **approximate** objective: $H_{\text{Betha}} = H(b_{i,j}, b_i)$
 - **relaxed** feasible set: $\mathcal{M}_o = \left\{ \tau \geq 0 \mid \sum_{x_i} \tau(x_i) = 1, \sum_{x_i} \tau(x_i, x_j) = \tau(x_j) \right\}$
- $$b^* = \arg \min_{b \in \mathcal{M}_o} \left\{ \langle E \rangle_b + F(b) \right\}$$
- The loopy BP algorithm:
 - a fixed point iteration procedure that tries to solve b^*